



Photoelectric sensors and photoelectric proximity sensors



Photoelectric proximity sensors

- Sender and receiver in one housing
- No reflector required
- Reacts to light reflected off object to be detected

Photoelectric proximity sensors, energetic

- Scanning range/switching point can be set by adjusting sensitivity



Photoelectric proximity sensors with foreground suppression (FGS)

- Detection of low objects, e.g. on conveyor belt. Objects, which reduce distance from scanning plane to sensor, are detected.



Photoelectric proximity sensors with background suppression (BGS)

- Detection of objects within a defined scanning range. Objects beyond this range are not detected.



Photoelectric reflex sensors

- Sender and receiver in one housing
- Different reflector sizes for different ranges and object sizes
- Large scanning ranges
- Polarisation filters also allow reflective objects to be detected
- Automatic sensitivity adjustment with "Teach-in" sensors



Through-beam photoelectric sensors

- Separate sender and receiver (2 devices)
- Very large scanning ranges
- High operating reserves
- Reliable detection of both transparent and reflective objects



Fibre-optic photoelectric sensors

- Sender and receiver in one housing
- 2 fibre-optic cables, scanning or through-beam principle possible
- Appropriate fibre-optic cable available for each task
- Especially suitable where installation space is limited and for use in hostile environments



Contents

Photoelectric sensors and photoelectric proximity sensors

The right sensor for your applications	page 466
Selection table	page 470

Photoelectric proximity sensors for roller conveyors

WTR/WLR/ZLM	page 906
-------------	----------

Miniature photoelectric sensors

W 2	page 474
W 4-3	page 490
W 100	page 518
W 140-2	page 538
W 150	page 548

Cylindrical photoelectric sensors

V 12-2	page 922
V 18	page 930
MH 15	page 958

Small photoelectric sensors

W 160	page 560
W 160T	page 586
W 170	page 616
WLL 170T	page 628
WT 190T	page 644
WLL 190T	page 654
W 9-2	page 662
W 11	page 688
W 12-2	page 702
W 14-2	page 728
W 18-3	page 740

Laser photoelectric switches

Review	page 976
WT 27L-2 Laser	page 978
W 100 L	page 980
W 9 L	page 988
W 130 L	page 996
W 190 L "Standard Series"	page 1010
W 190 L "High Grade"	page 1020
W 12L-2 Laser	page 1030
V 18 Laser	page 1038

Standard photoelectric sensors

W 23-2	page 758
W 24-2	page 770
W 250	page 788
W 260	page 810
W 280	page 840
W 27-3	page 854
W 34	page 874
W 45	page 892

Ex photoelectric sensors

Review	page 1046
--------	-----------

Category 2

W 24 Exi (incl. ATEX)	page 1048
-----------------------	-----------

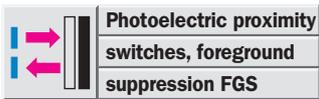
Category 3

WT 18-3 Ex (incl. ATEX)	page 1060
W 27-3 Ex (incl. ATEX)	page 1064
WTR 2 Ex (incl. ATEX)	page 1070
WL 24-2 Ex (incl. ATEX)	page 1072

Photoelectric sensors and photoelectric proximity sensors →

The right sensor for your applications

With photoelectric proximity switches (e.g. WT 24-2), the emitted light is reflected by the detected object itself, received and then evaluated.



Photoelectric proximity switches with foreground suppression are able to detect objects within a defined scanning distance.

All objects between the scanning distance (set to the background) and the scanner itself are detected above a minimum size. Suppression of the foreground is achieved by means of a special geometri-

cal arrangement of sender and receiver elements. To ensure that these switches can function reliably, the background (e.g. a conveyor belt) must be relatively light in colour and its height must not fluctuate.



The operating principle of photoelectric proximity switches with background suppression is based on the geometrical relationship between the sender and receiver elements. The switch is adjusted to the object located in the scanning plane. Signals from

objects which are behind the set scanning plane are suppressed.

Photoelectric proximity switches with background suppression can be negatively influenced by high-gloss objects in the background, e.g. glass panels, polished sheet metal and so on.

These effects can increase if the background within the specified sensor's scanning distance is not defined. This problem can be solved by screening off or tilting the devices.

High resolutions are possible using laser diodes so that small objects can be detected precisely and reliably. Light

spot diameters of 0.1 mm for example.

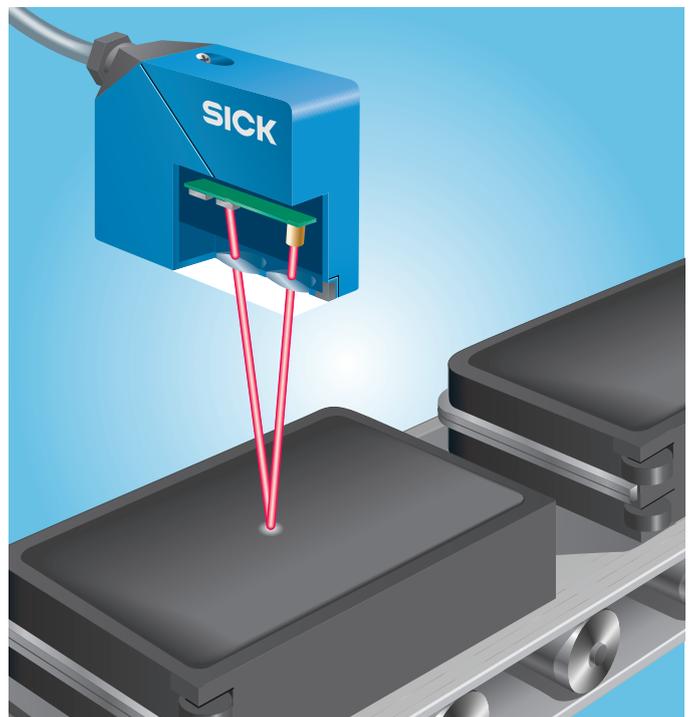


Background blanking for photoelectric proximity switches is achieved either electronically or optically. In the optical method the angle between the sender and receiver light beam is adjusted while setting the scanning distance to the object. Objects are detected at the point where the emitted beam is reflected back directly to the receiver element. Anything lying below this point remains undetected as no light, or too little, reaches the receiver element.

▼ FGS – foreground suppression



▼ BGS – background suppression



▼ BGB – background blanking

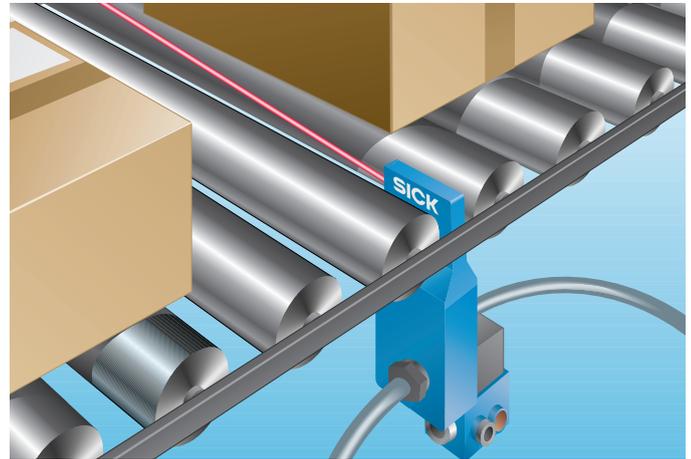


In the electronic method PSD elements (Position Sensitive Devices) are used. The emitted light beam is reflected by the object and hits the PSD receiver. Depending on the position of the reflected light beam, the incoming signal is recognised as being a background signal and electronically suppressed.



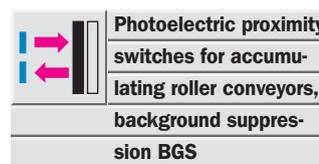
The least expensive solution is the energetic photoelectric proximity switch with adjustable sensitivity. A light surface reflects more light than a dark surface and can, therefore, be detected from a greater distance. In order to achieve similar results with a dark surface, the sensitivity of the switch must be increased. The detection of a dark object in front of a light background is a problem for energetic switches. Owing to its higher remission, the background

▼ Accumulating roller conveyors



“outshines” the object. The switches are, however, ideal for detecting a light object in front of a dark background.

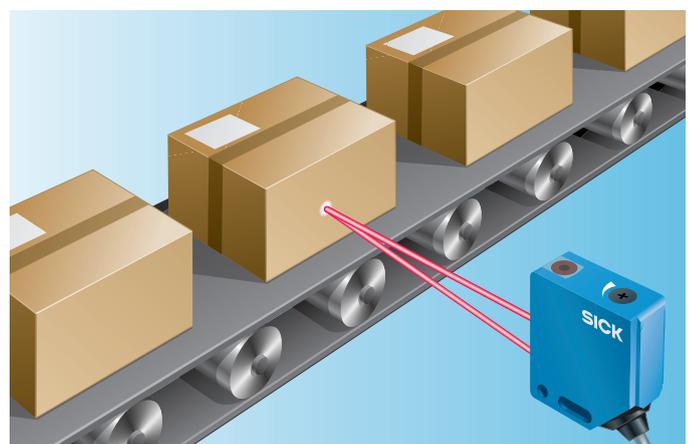
conveyed object from between the rollers. The detection signal is evaluated in the logic unit and the electro-pneumatic cylinder is actuated via the valve.



These non-contact photoelectric proximity switches, which were specially developed for handling systems, detect the

Use of these switches automatically fulfils the principle of accumulating conveyor systems without the need for additional control elements.

▼ Photoelectric proximity switch



The right sensor for your applications



Photoelectric reflex switches

With the photoelectric reflex switches (e.g. WL 24-2), the emitted light beam is reflected by a reflector and then received and evaluated by the device.

Polarisation filters prevent incorrect operation when reflective objects are detected. Transparent films and shrink-wrap may influence the way in which the reflex photoelectric switches with polarisation filters function. Devices with reduced sensitivity solve this problem.

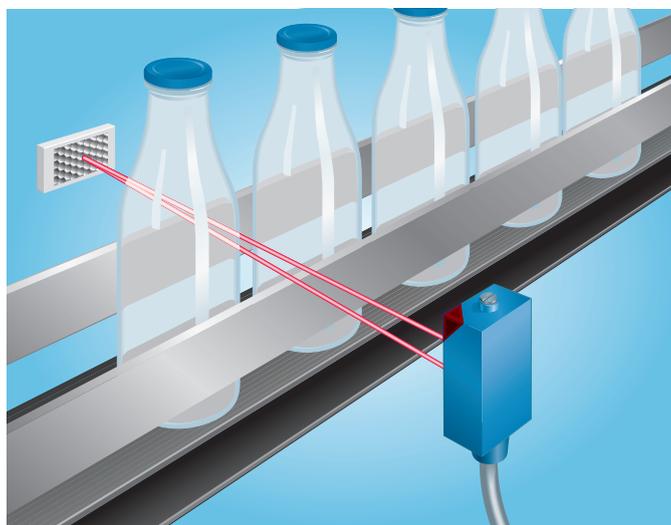
The use of laser diodes allows greater scanning ranges while simultaneously maintaining a high resolution. Focus ranges can be set with high precision.



Photoelectric reflex switches for detecting transparent objects

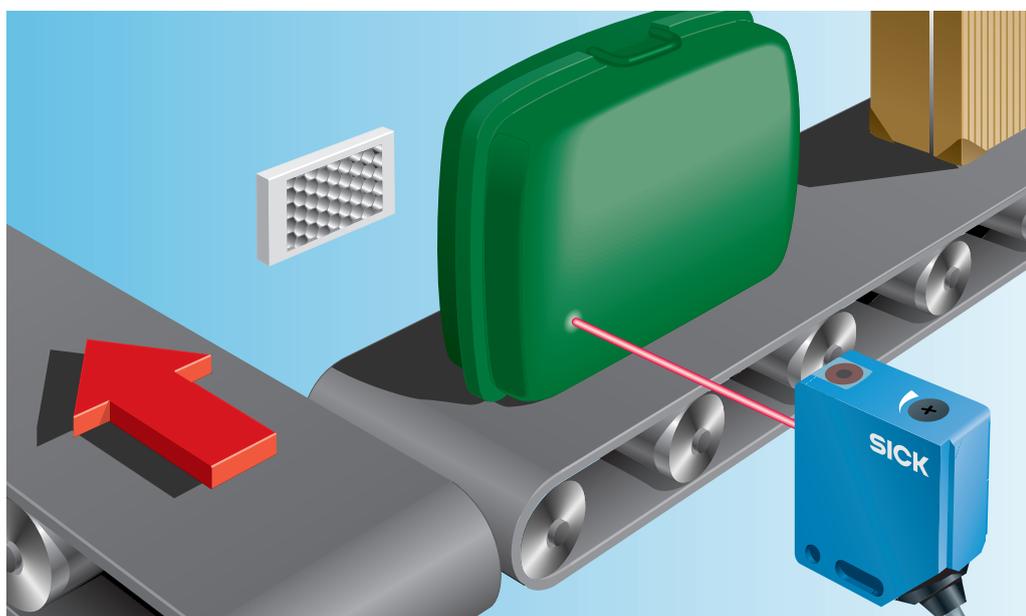
These reflex photoelectric switches are characterised by their extremely low switching hysteresis. Even low levels of light between the sensor and reflector, caused by e.g. glass bottles or even PET bottles, are detected reliably.

▼ Detection of transparent objects



A newly developed system checks and continually adjusts the switching threshold electronically to adapt to the gradual accumulation of dirt, which would otherwise lead to a system failure.

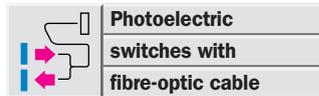
▼ Photoelectric reflex switch





The through-beam photoelectric switch consists of two devices: the sender (e.g. WS 24-2) and receiver (e.g. WE 24-2).

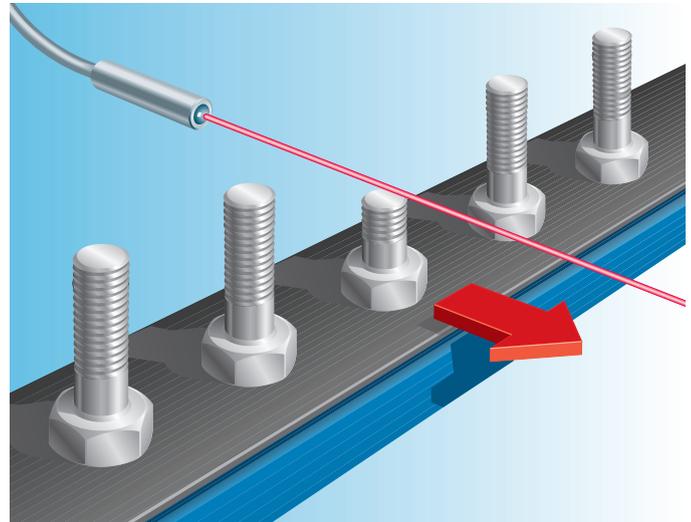
The separate device configuration makes large scanning ranges possible. The use of laser diodes allows greater scanning ranges while simultaneously maintaining a high resolution. Focus ranges can be set with high precision.



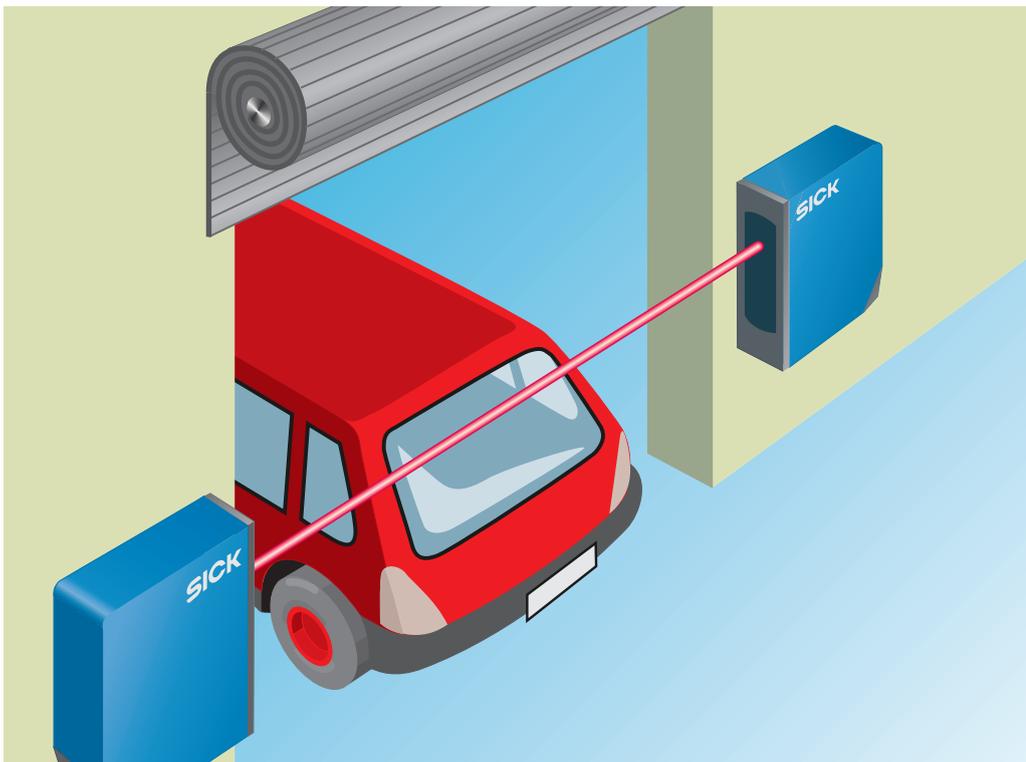
In the case of photoelectric switches with fibre-optic cable (e.g. WLL 12), the sender and receiver are contained in a single housing.

A separate fibre-optic cable is used for the sender and the receiver for operation as a through-beam system. For use as a proximity switch the sender and receiver fibre-optic cables are combined in one cable.

▼ Photoelectric switch with fibre-optic cable

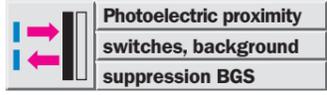


▼ Through-beam photoelectric switch





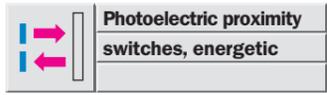
Type	Scanning distance, max. typical in mm	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WT 11	35 – 100																		690
WT 12-2	35 – 100																		704
WTB 190 TL	40 – 270																		1022
WTV 190T	80 – 300																		646



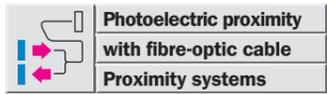
Type	Scanning distance, max. typical in mm	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WT 2	1 – 30																		476
WT 150	2 – 100																		550
WT 4-3 Teflon	4 – 120																		502
VT 18	25 – 140																		932
WT 4-3	4 – 150																		492
WT 160T	15 – 150																		588
WT 9 L	30 – 150																		998
WT 12 L-2	30 – 200																		1032
WT 9-2	30 – 250																		664
WT 11	20 – 250																		692
WT 12-2	20 – 250																		706
WTB 190 TL	40 – 270																		1022
WTB 190T	80 – 300																		650
WTB 190 L	40 – 300																		1012
WTB 140	2 – 500																		540
WTR	300 – 900																		912
WT 18-3	50 – 1000																		742
WT 250	200 – 1000																		790
WTB 27-3	30 – 1600																		856
WT 24 Exi	100 – 2000																		1050
WT 45	400 – 2000																		894
WT 260	7 – 2100																		812
WT 24-2	100 – 2500																		772
WT 34	100 – 2500																		876



Type	Scanning distance, max. typical in mm	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WT 160	4 – 60																		562
WT 170	10 – 100																		618
VT 18	3 – 100																		934
WT 100	4 – 140																		520
WT 9-2	30 – 500																		668
WT 14-2	80 – 500																		730
WT 23-2	50 – 1000																		760



Type	Scanning distance, max. typical in mm	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WT 2	1 – 55																		478
WT 150	10 – 250																		552
VT 12-2	0 – 340																		924
MHT 15	10 – 350																		960
VTE 18 L	0 – 400																		1040
WT 100 L	0 – 450																		982
WT 170	10 – 550																		620
VT 18	3 – 800																		936
WT 100	0 – 900																		522
WT 12-2	10 – 1000																		712
WTE 140-2	0 – 1000																		542
WT 160	0 – 1000																		566
WT 11	10 – 1000																		694
WT 130 L	0 – 1200																		998
WTE 160T	0 – 1300																		604
WT 9-2	50 – 1500																		670
WT 14-2	300 – 1500																		734
WT 280	10 – 1700																		842
WT 23-2	50 – 2300																		764
WT 260	10 – 3500																		820



Type	Scanning distance, max. typical in mm	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WLL 24 Exi	0 – 25																		1056
VLL 18T	0 – 50																		950
WLL 260	0 – 65																		836
WLL 160 (T)	0 – 70																		582
WLL 170 (H/A/T)	0 – 160																		630
WLL 12	0 – 280																		726
WLL 190T	0 – 300																		656

¹⁾ Pre-failure signalling output · ²⁾ UC devices only · ³⁾ TRIAC output · ⁴⁾ Also with analogue output

Photoelectric reflex switches

Type	Scanning range, max. typical in m	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WL 2	0.04 - 0.8																		484
WL 160T	0.03 - 2.2																		612
WL 150	0.005 - 2.4																		554
VL 12-2	0.03 - 2.8																		926
VL 18	0.05 - 3.7																		938
WL 4-3	0.01 - 4																		504
WL 170	0.01 - 4																		622
WL 9-2	0 - 4																		678
WLR 1	0.25 - 5																		918
MHL 15	0.035 - 5																		968
WL 190 L	0.01 - 5.5																		1016
WLG 190 T	0.01 - 5.5																		1026
WL 100	0.01 - 6																		524
WL 14-2	0.15 - 6																		736
WL 140-2	0.01 - 6.5																		544
WL 160	0.01 - 6.5																		574
WL 11	0 - 7																		696
WL 12-2	0 - 7																		714
WL 18-3	0 - 7																		752
WL 23-2	0.1 - 10																		766
WL 130 L	0 - 10																		1000
WL 100 L	0 - 12																		984
WL 9 L	0.1 - 12																		992
WL 250	0.01 - 13.5																		802
WL 27-3	0.1 - 15																		866
WL 24 Exi	0 - 15																		1052
WL 260	0.01 - 15																		828
WL 280	0.01 - 15																		846
WL 12 L-2	0 - 18																		1034
WL 24-2	0 - 22																		780
WL 34	0 - 22																		884
VL 18 L	0.1 - 35																		1042
WL 45	0.01 - 55																		898

Through-beam photoelectric switches

Type	Scanning range, max. typical in m	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WS/WE 2	0 - 1.2																		486
WSE 4-3 Teflon	0 - 3																		516
WS/WE 130 L	0 - 3.5																		1002
WS/WE 150	0 - 4.4																		558
WSE 4-3	0 - 5.5																		512
VS/VE 12-2	0 - 5																		928
MHSE 15	0 - 5																		972
WS/WE 9-2	0 - 7																		686
WS/WE 170	0 - 8.5																		626
WS/WE 160	0 - 15																		578
WS/WE 100	0 - 15																		532
WS/WE 14-2	0 - 15																		738
WS/WE 140-2	0 - 16																		546
WS/WE 12-2	0 - 20																		724
WS/WE 18-3	0 - 20																		756
VS/VE 18	0 - 20																		940
WS/WE 250	0 - 25																		806
WS/WE 100 L	0 - 35																		986
WSE 27-3	0 - 35																		870
WS/WE 24 Exi	0 - 40																		1054
WS/WE 260	0 - 45																		832
WS/WE 280	0 - 45																		850
WS/WE 190 L	0 - 50																		1018
WS/WE 9 L	0 - 50																		994
WS/WE 24-2	0 - 60																		784
WS/WE 34	0 - 60																		888
VS/VE 18 L	0 - 60																		1044
WS/WE 12 L-2	0 - 80																		1036
WS/WE 45	0 - 350																		902

Photoelectric switches with fibre-optic cable Through-beam system

Type	Scanning range, max. typical in mm	Light type				Equipment		Equipment		Supply voltage			Output		Connection			from page	
		Red	Infrared	Green	Laser	Testing	Time del.	VMA ¹⁾	Heating	DC	AC	UC	NPN/PNP	Relay	Plug	Cable	Terminals		
WLL 24 Exi	0 - 100																		1056
WLL 18T	0 - 200																		950
WLL 12	0 - 280																		726
WLL 260	0 - 800																		836
WLL 190T	0 - 1300																		656
WLL 160 (T)	0 - 2000																		582
WLL 170 (H/A/T)	0 - 4000																		630

¹⁾ Pre-failure signalling output · ²⁾ UC devices only · ³⁾ TRIAC output · ⁴⁾ Also with analogue output  = Glass detection