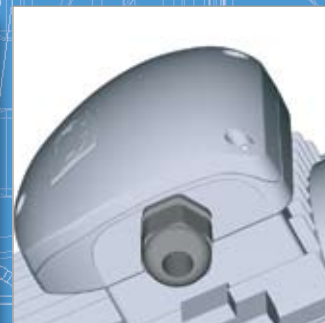
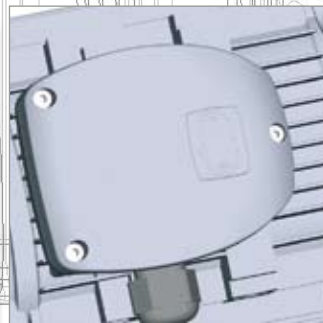
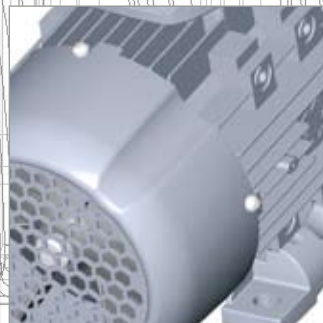
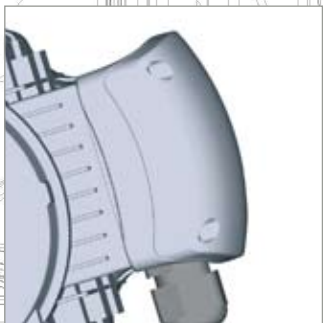


DELPHI SERIES ASYNCHRONOUS THREE-PHASE ELECTRIC MOTORS





VISIT AND KNOW MOTIVE THANKS TO THE MOVIE ON WWW.MOTIVE.IT



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Three-phase self-braking motors series atdc delphi pag. 14

Delphi AT pag. 15



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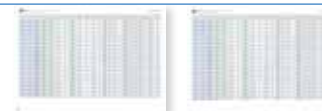
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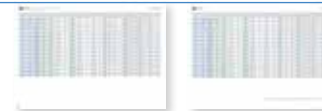
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Rubber seal rings and bearings pag. 33



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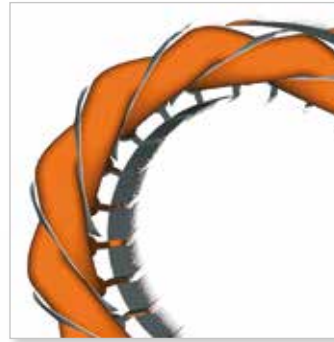
TECHNICAL CHARACTERISTICS

Motive motors are built according to international standard regulations; each size throughout the construction forms is calculated with reference to the tables of standard IEC 72-1.

Motive asynchronous three-phase delphi series motors are closed, and externally ventilated. The frame, up to 132 included, is made in die casting aluminium alloy, from size 160 up to 355 the frame is made in cast iron.

All motors are
multiple voltage
multi-frequency 50/60Hz,
F class insulation, (H on request)
S1 continuous duty service,
IP55 protection (IP56, 66 and 67 on request)
IE2 or IE3 efficiency class (IEC 60034-30)
tropicalized winding
suitable for inverter power supply

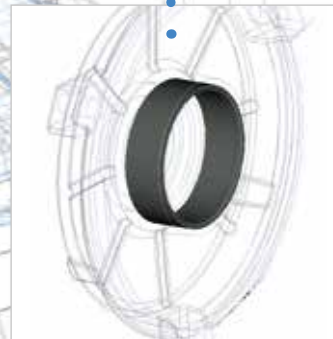
IE2, high efficiency class IEC 60034-30
IE3, premium efficiency class IEC 60034-30



The copper is impregnated with a double layer of H class insulating enamel to ensure high resistance to electrical, thermal and mechanical stress. The phases are further isolated by another layer of Nomex film to protect the motors from the voltage peaks that usually occur when the motor is controlled by an inverter.

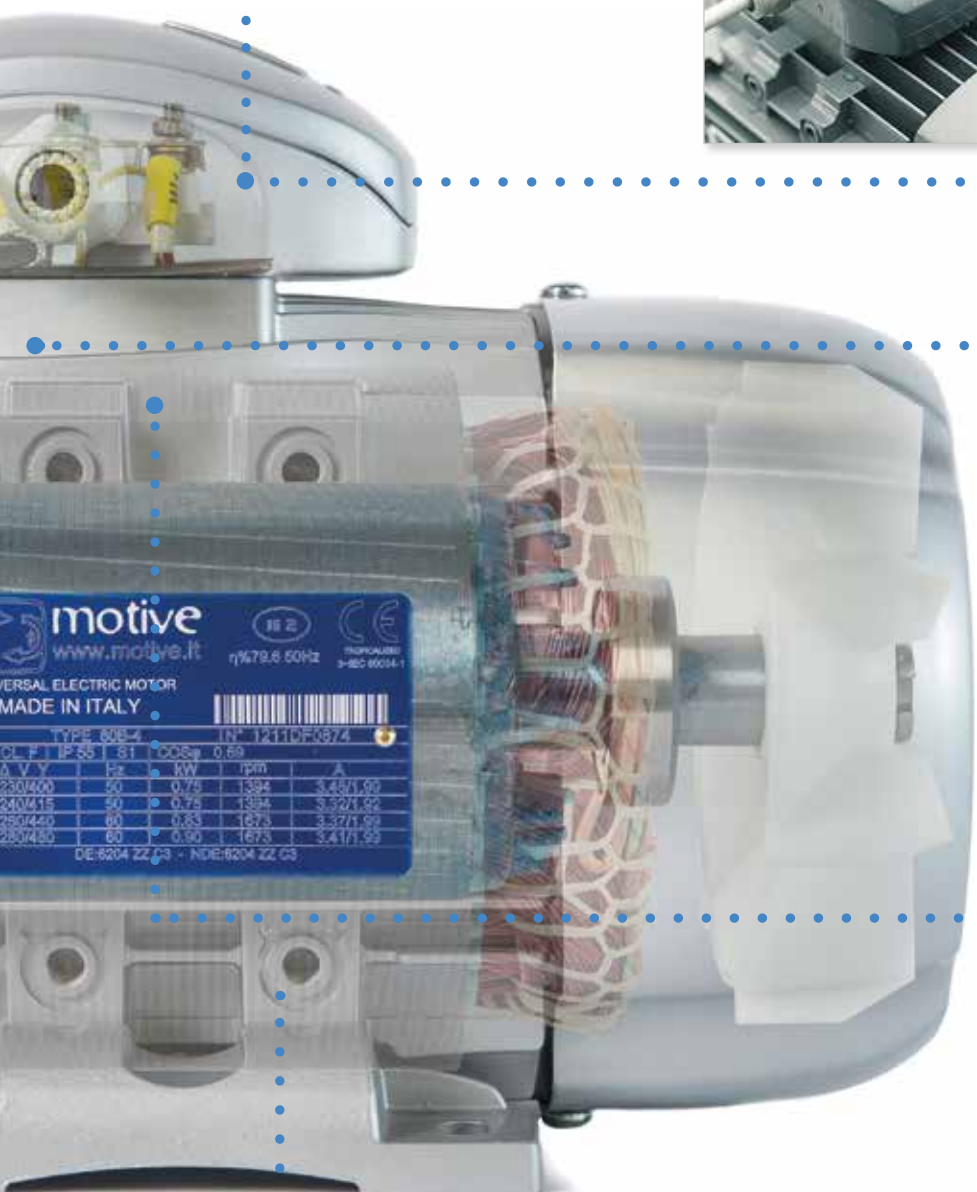


Motive motors adopt only bearings selected for their silence and reliability and, for the same objectives, the cage rotor is dynamically balanced according to IEC 34-14 and ISO 8821 norms

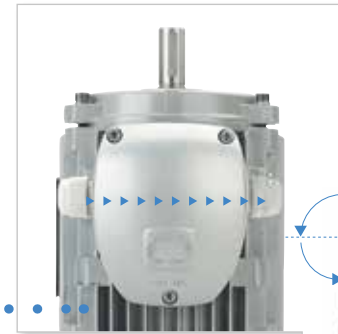


From type 90, a steel insert is provided in the bearing slot of the aluminum flanges, to resist to radial mechanical forces with a fair degree of security

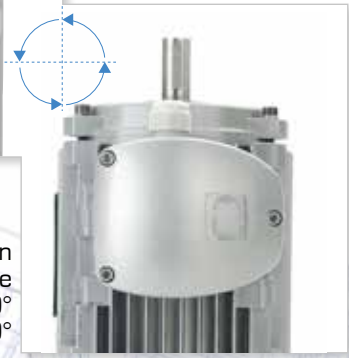
REGISTERED DESIGN



Aiming the maximum protection, the motors are equipped with important details like the pull-resistant cable gland and the combination of bearings with two shields each with rubber seal rings



Cable gland can be easily moved on both the sides of the connection box, thanks to the screw cap

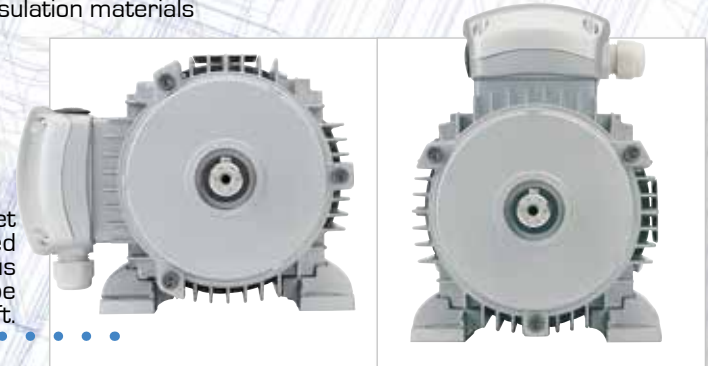


The connection box can be rotated of 360° with steps of 90°

To protect them by the rust, motive motors are painted in silver RAL9006 colour



Performance excellence is granted by the low loss CRNO "FeV" magnetic laminations adoption, instead then the usual Semi Processed/Decarb "FePO1". FeV laminations provide higher efficiency, lower heating, energy saving and longer life to insulation materials



From size 56 to size 132, feet are detachable, and can be fixed on 3 sides of the housing, thus permitting the terminal box to be positioned up, right or left.

motive
www.motive.it

UNIVERSAL ELECTRIC MOTOR
MADE IN ITALY

CL	F	IP	55	81	COSφ	0.69
Δ	V	Y	P ₂	kW	rpm	A
230	400	50	0.75	1394	3.450	50
230	415	50	0.75	1394	3.520	50
250	440	60	0.83	1673	3.370	50
250	450	60	0.90	1673	3.410	50

TYPE 60B4 IN° 12110F0374
DE:6204 ZZ G3 - NDE:6204 ZZ G3

EFFICIENCY

Worldwide there are several classification systems of induction motors efficiencies. In order to create a common system, IEC (International Electrotechnical Commission) issued in October 2008 the norm IEC 60034-30 "Rotating electrical machines – Part 30: Efficiency classes of single-speed, three-phase, cage-induction motors (IE-code)". It's a classification system of efficiency that replaces the CEMEP one (to be clear, the one of "Eff.1, Eff.2, ed Eff.3" motors) and that, furthermore, recalls a new measuring and calculation way of efficiency, the one of the norm IEC 60034-2-1 (Rotating electrical machines – Part 2-1: Standard methods for determining losses and efficiency from tests), of September 2007.

In Europe it's a step ahead in the application of the Eco-design Directive for Energy-related Products (ErP) 2009/125/EC. It's based on such a normative picture and on the Regulation (EC) nr 640/2009 of 22 July 2009 that:

- From June 2011, the motors with efficiency lower than IE-2 have been forbidden
- From 2015, the minimum efficiency for motors not equipped with an electronic variable speed drive from 7,5 to 375kW will be IE-3, and
- From 2017, the obligation of IE-3 will be extended to the motors not equipped with an electronic variable speed drive from 0,75kW to 5,5kW

IEC classification and CEMEP classification

KW	Hp	efficiency classes IEC 60034-30:2008 (at 50Hz)									efficiency classes CEMEP voluntary agreement					
		IE-1 standard efficiency			IE-2 high efficiency			IE-3 premium efficiency			Eff.3		Eff.2		Eff.1	
		2 poles	4 poles	6 poles	2 poles	4 poles	6 poles	2 poles	4 poles	6 poles	2 poles	4 poles	2 poles	4 poles	2 poles	4 poles
0,75	1	72,1	72,1	70,0	77,4	79,6	75,9	80,7	82,5	78,9	-	-	-	-	-	-
1,1	1,5	75,0	75,0	72,9	79,6	81,4	78,1	82,7	84,1	81,0	<76,2	<76,2	≥76,2	≥76,2	>82,8	>83,8
1,5	2	77,2	77,2	75,2	81,3	82,8	79,8	84,2	85,3	82,5	<78,5	<78,5	≥78,5	≥78,5	>84,1	>85,0
2,2	3	79,7	79,7	77,7	83,2	84,3	81,8	85,9	86,7	84,3	<81,0	<81,0	≥81,0	≥81,0	>85,6	>86,4
3	4	81,5	81,5	79,7	84,6	85,5	83,3	87,1	87,7	85,6	<82,6	<82,6	≥82,6	≥82,6	>86,7	>87,4
4	5,5	83,1	83,1	81,4	85,8	86,6	84,6	88,1	88,6	86,8	<84,2	<84,2	≥84,2	≥84,2	>87,6	>88,3
5,5	7,5	84,7	84,7	83,1	87,0	87,7	86,0	89,2	89,6	88,0	<85,7	<85,7	≥85,7	≥85,7	>88,6	>89,2
7,5	10	86,0	86,0	84,7	88,1	88,7	87,2	90,1	90,4	89,1	<87,0	<87,0	≥87,0	≥87,0	>89,5	>90,1
11	15	87,6	87,6	86,5	89,4	89,8	88,7	91,2	91,4	90,3	<88,4	<88,4	≥88,4	≥88,4	>90,5	>91,0
15	20	88,7	88,7	87,7	90,3	90,6	89,7	91,9	92,3	91,2	<89,4	<89,4	≥89,4	≥89,4	>91,3	>91,8
18,5	25	89,3	89,3	88,6	90,9	91,2	90,4	92,4	92,6	91,7	<90,0	<90,0	≥90,0	≥90,0	>91,8	>92,2
22	30	89,9	89,9	89,2	91,3	91,6	90,9	92,7	93,0	92,2	<90,5	<90,5	≥90,5	≥90,5	>92,2	>92,6
30	40	90,7	90,7	90,2	92,0	92,3	91,7	93,3	93,6	92,9	<91,4	<91,4	≥91,4	≥91,4	>92,9	>93,2
37	50	91,2	91,2	90,8	92,5	92,7	92,2	93,7	93,9	93,3	<92,0	<92,0	≥92,0	≥92,0	>93,3	>93,6
45	60	91,7	91,7	91,4	92,9	93,1	92,7	94,0	94,2	93,7	<92,5	<92,5	≥92,5	≥92,5	>93,7	>93,9
55	75	92,1	92,1	91,9	93,2	93,5	93,1	94,3	94,6	94,1	<93,0	<93,0	≥93,0	≥93,0	>94,0	>94,2
75	100	92,7	92,7	92,6	93,8	94,0	93,7	94,7	95,0	94,6	<93,6	<93,6	≥93,6	≥93,6	>94,6	>94,7
90	120	93,0	93,0	92,9	94,1	94,2	94,0	95,0	95,2	94,9	<93,9	<93,9	≥93,9	≥93,9	>95,0	>95,0
110	150	93,3	93,3	93,3	94,3	94,5	94,3	95,2	95,4	95,1	-	-	-	-	-	-
132	180	93,5	93,5	93,5	94,6	94,7	94,6	95,4	95,6	95,4	-	-	-	-	-	-
160	220	93,8	93,8	93,8	94,8	94,9	94,8	95,6	95,8	95,6	-	-	-	-	-	-
200	270	94,0	94,0	94,0	95,0	95,1	95,0	95,8	96,0	95,8	-	-	-	-	-	-
250	335	94,0	94,0	94,0	95,0	95,1	95,0	95,8	96,0	95,8	-	-	-	-	-	-
315	423	94,0	94,0	94,0	95,0	95,1	95,0	95,8	96,0	95,8	-	-	-	-	-	-
355	483	94,0	94,0	94,0	95,0	95,1	95,0	95,8	96,0	95,8	-	-	-	-	-	-

The following chart tries to synthesize a comparison between yesterday and today.

	world IEC 60034-30	Europe (50Hz) CEMEP	USA (60Hz) Epact	Further classification
IE-3 premium efficiency			Identical to NEMA Premium efficiency	AS in Australia NBR in Brasile BG/T in China IS in India JIS in Japan MEPS in Korea
IE-2 high efficiency		comparable to Eff. 1	Identical to NEMA energy efficiency/EPACT	
IE-1 standard efficiency		comparable to Eff. 2		

In our field, we list 5 main changes in Europe :

- The classification is now extended to 6 poles motors
- The powers range is wider
- In a direct comparison between Eff.2" and "IE-1" or between "Eff.1" and "IE-2" , we find that the first, the CEMEP values, are higher, but this is also a consequence of the
- Change in the measurement and calculation system of such values, that must now be made with the method of the new norm IEC 60034-2-1:2007, and
- Introduction of the IE3 "Premium efficiency" level.

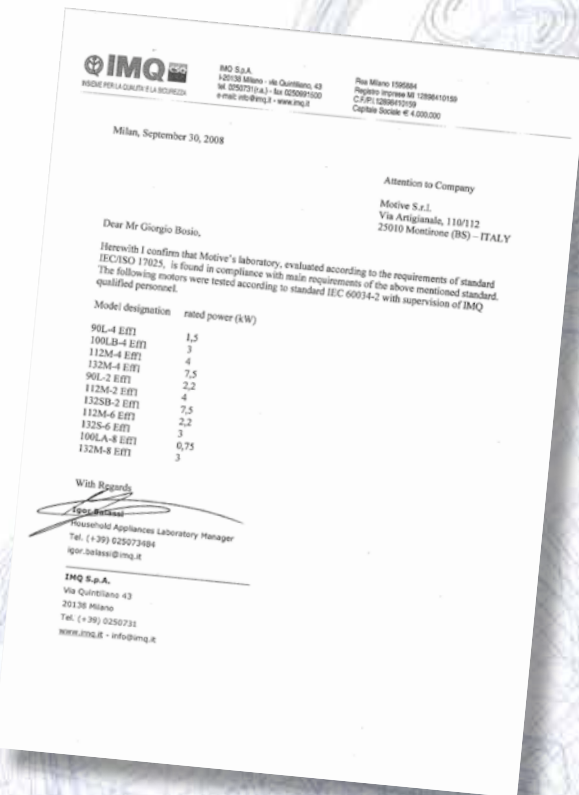
Nevertheless, local legislations of some Countries inside and outside Europe, and the specific requirements of some associations, maintain often incentivized or even compulsory those motors called "Eff.1" according to the CEMEP system.

What did Motive do in this scenario?

- The measuring and calculation system of Motive motors efficiency is conform to the norm 60034-2-1:2007. That's the one behind the data declared in the probative test-reports uploaded in motive web-site (each declared data, we remind it, is in fact supported, detailed and proven by such test reports)

- This, together with the fact that Eff.2 Motive motors were often offering an efficiency abundantly above the min allowed level, permitted us to reach easily IE2 efficiency with a two years long R&D plan before June 2011. From June 2011, IE1 motors are not produced anymore.
- IE3 "premium efficiency" motors are also available.

- The testing system, test reports, and data truth of Motive motors has been certified by IMQ, the main Italian certification body for electrical appliances. The same, in fact, has firstly inspected



and qualified our internal laboratory according to the norm IEC/ISO17025, and then supervised the internal tests on a sampling list of motors.

Clients benefits are of many kinds:

BILL EFFECTS

The purchase cost of a motor is about 2-3% of the total costs of its life. The balance is energy consumption costs. Comparing IE3 motors to IE2, the purchase price difference is recovered in about one year of energy saving. Of course, such period length depends by the specific motor, the use of it and the local energy costs of each Country. Motive can give you a tool in xls format to support you in this calculation.

DURABILITY EFFECTS

Higher efficiency motors heat less, slowing down the aging cycle of the insulating materials and living longer.

The average life is approximately from 35 to 40,000 hours for IE2 motors up to 15kW and 60,000 for IE2 bigger motors. IE3 motors can live approx 40% longer than IE2 motors.

AMBIENT EFFECTS

Electric motors use 65% of all electricity in industry. Higher efficiency motors have the further objective of sustainable development, reduction of CO₂ emissions and consequent improvement of the quality of the atmosphere with an objective of sustainable development, Reduction of CO₂ emissions and consequent improvement of the quality of the atmosphere.

How to make a more efficient motor?

High efficiency can be seen in many ways: like the relation between output power and input absorbed power, or like a measure of the losses that born when converting the electric power in mechanical energy. From another perspective, high efficiency motors consume less energy to produce the same torque on the shaft. Basically, an high efficiency motor is the result of precise machining, lower frictions, a dynamically balanced rotor, smaller space between rotor and stator and of the use of better materials. The main factors for the design are based on the choice of the type of lamination sheets and windings with a greater turns number and a bigger diameter wire.

Among all materials that compose a motor, laminations have the highest influence on performance.

Motive motors are made with CRNO "FeV" magnetic lamination sheets, rather than the customary iron lamination sheets.

Further than raw material, the sheets thickness is another performance source . In fact, the thinner is the sheet, the higher are the performances.

The Semi Processed/Decarb lamination sheets "Fe PO1" can reach up to 1mm thickness.

FeV magnetic lamination sheets have a 0,5mm maximum thickness.

Composition and thickness give to magnetic lamination sheets a very low W/Kg loosing factor:

Lower specific losses mean less magnetising current for the same Power and torque (thus less heating).

Instead, no standard prescribes a maximum loosing factor for Fe PO1 lamination sheets; not even this data can be guaranteed. This is a source of potential performance diversities between motor and motor.






The main advantages given by the adoption of silicon magnetic laminations are: higher efficiency better guarantees on the quality consistency, assured by tolerances reported in international norms.








CE marking is referred to:

-  Low Voltage 06/95 EEC
-  EMC Electromagnetic Compatibility 04/108/EEC
-  Eco-design Directive for Energy-related Products (ErP) 2009/125/EC


Note: The Machinery Directive (MD) 2006/42/EC excludes from its scope the electric motors [Art.1, comma 2]

CE marking is put by Motive as a visible sign of the product compliance with the requirements of above mentioned directives. In order to reach this conformity, Motive products respect the following product standards:

-  EN 60034-1 (last issue). Rotating electrical machines. Part 1: rating and performance
-  EN 60034-5 (last issue). Rotating electrical machines. Part 5: classification of degrees of protection
-  EN 60034-6 (last issue). Rotating electrical machines. Part 6: methods of cooling (IC code)
-  EN60034-7 Rotating Electrical Machines - Part 7: Classification of Types of Construction, Mounting Arrangements and Terminal Box Position (IM Code)
-  EN60034-8 Rotating electrical machines-Part 8: Terminal markings and direction of rotation





-  EN60034-2-1 (last issue). Rotating electrical machines. Standard methods for determining losses and efficiency from tests
-  EN60034-30 (last issue). Rotating electrical machines - Part 30: Efficiency classes of single-speed, three-phase, cage-induction motors
-  EN50347 General purpose three-phase induction motors having standard dimensions and outputs. Frame numbers 56 to 315 and flange numbers 65 to 740
-  EN60335-1 Household and similar electrical appliances - Safety
-  EN61000-6-4 Electromagnetic compatibility (EMC) - Part 6: Generic standards - Section 4: Emission standard for industrial environments
-  EN 60034-9 (last issue). Rotating electrical machines. Part 9: noise limits
-  EN60034-25 Rotating electrical machines - Part 25: Guidance for the design and performance of a.c. motors specifically designed for converter supply



 II 3 GD Ex nA T4 Ex tD A22 IP65 125°C

ATEX is the conventional name of the Directive 94/9/EC for the equipment intended for use in potentially explosive atmospheres. The name comes from the words ATmospheres and Explosibles. It became compulsory in all the European Union from 1st March 1996, imposing the evaluation of the risk for all the equipment operating in such environments. It classifies several levels of "danger" (zones): to every zone it corresponds a different typology of explosive atmosphere, according to its composition and to its probability and time of appearance. The client is responsible of the choice of the right motor based on the criteria described in the norm EN 61241-14.

Motive delphi Ex motors are designed to be used in the zone 22 (II 3 D T125°) and/or zone 2 (II 3 G T125°), according to the classification stated in the plate, and for the voltage and frequency field A described by the norm EN 60034 part 1 Cap. 6.3.

-  EN60079-0 Electrical apparatus for explosive gas atmospheres - Part 0: General requirements
-  EN60079-15 Electrical apparatus for explosive gas atmospheres - Part 15: Construction, test and marking of type of protection, "n" electrical apparatus
-  EN60079-31 Explosive atmospheres Part 31: Equipment dust ignition protection by enclosure "t"
-  EN50281-2-1 Electrical apparatus for use in the presence of combustible dust. Test methods. Methods of determining minimum ignition temperatures

PROTECTION TYPE

The protection against people accidental contacts and/or the entry of corps and/or the entry of water is expressed at international level (EN60529) by a symbolic acronym composed by a group of 2 letters and 2 numbers.

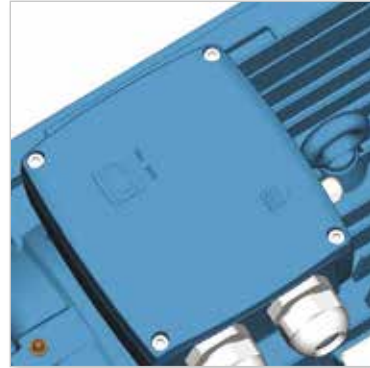
IP index of protection reference letters

1° num. Protection of people against contacts and protection against the entry of solid corps

2° num. Protection against harmful entry of water

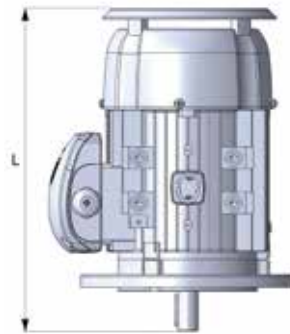
Motive motors are IP55 protected

	1° number	2° number
	0 no protection	no protection
	1 protection against solid corps bigger than 50mm	protection against vertical water drops
	2 protection against solid corps bigger than 12mm	protection against water drops fall up to 15° of inclination
	3 protection against solid corps bigger than a 2,5mm	protection against water drops up to 60° of inclination
	4 protection against solid corps bigger than 1 mm	protection against water sprayed by all directions
STANDARD	5 protection against harmful dust deposits	protection against water launched by a nozzle of 6,3mm D with a water capacity 12,5lt/min at a distance of maximum 3 mt for 3 min
OPTIONAL	6 complete protection against the total penetration of dust	protection against water projections similar to sea waves
OPTIONAL	7	protection from temporary submersion in water, up to 1 meter in depth
OPTIONAL	8	protection from extended periods of immersion, up to a specific depth



RAIN SHIELD OR CLEAN FLOW FAN COWL FOR TEXTILE INDUSTRY

For outdoor applications with V5 - V18 - V1 - V15 installation, we recommend to mount a rain shield. This configuration may also be used in textiles processing industry.

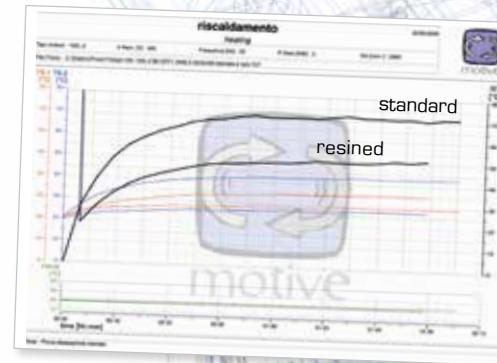


TYPE	L
63	215
71	323
80	369
90S	403
90L	428
100	469
112	453
132S	573
132M	613
160M	770
160L	825
180M	915
180L	955
200L	1025
225S	1155
225M	1160
250M	1220
280S	1265
280M	1315
315S	1540
315M	1570
315L	1680
355M	1840
355L	1870
400	2290



TOTAL SEALING

Resin coated stator is a safe solution to the presence of very strong humidity or aggressive environments (for instance, carwash systems or chemical plants). It offers also a lower heating thanks to the thermal dissipation capacity of the resin.

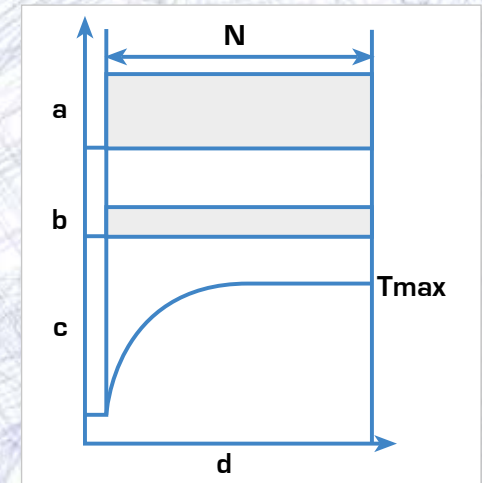


DUTY SERVICE

All Motive motors shown in this catalogue are made for S1 continuous duty service, as per IEC 34-1 norm. The duty service class is shown on the rating plate.

Below are described the various types of service:

S1 - Continuous service: operating at constant load of duration N in order to reach a thermal balance.



- a = load
- b = electric losses
- c = temperature
- d = time
- N = steady load operating time
- Tmax = max temperature achieved

- S2 - Limited-duration service.
- S3 - Periodic intermittent service.
- S4 - Periodic intermittent service with start-up.
- S5 - Periodic intermittent service with electric braking.
- S6 - Uninterrupted load periodic service with intermittent load.
- S7 - Uninterrupted periodic service with electric braking.
- S8 - Uninterrupted periodic service with correlated load and velocity variations.
- S9 - Service with non-periodic variations in load and speed.

The ideal combination is the resin-filled terminal box. In this case, according to the customer needs, the terminal block can be partially immersed, or totally immersed in such insulating and protective resin. In alternative, the terminal box and block can be taken off and the motor frame be closed by a sealed plate from which a cable can come out.

Note: rotors are painted against oxidation as a standard

WORKING CONDITIONS

HUMIDITY:

The electrical equipment must be able to work with a relative humidity between 30 and 95% (without condensation). Damaging effects of occasional condensation must be avoided by adequate equipment design or, if necessary, by additional measures (for example, Motive offers anti-condensation heaters, drain holes, resin coated stators, and resin filled terminal boxes).

ALTITUDE AND TEMPERATURE:

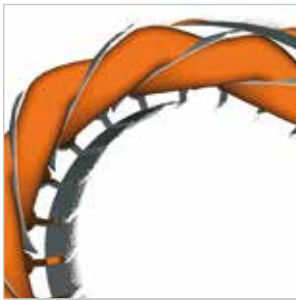
the powers indicated are intended for regular use at altitudes below 1000 mt above sea level and a room temperature between +5°C and +40°C for motors having a rated power below 0.6 kW, or between -15°C and 40°C for motors having a rated power equal to or greater than 0.6 kW (IEC 34-1): For working conditions rather than those specified (higher altitude and/or temperature) the power decreases of 10% each 10°C of higher temperature, and of 8% for each 1000 mt of higher altitude.

It is not necessary to reduce the rated power if at an altitude higher than 1000mt and lower than 2000mt there is a max ambient temperature of 30°C or, in altitudes from 2000 mt to 3000mt there is a max ambient temperature of 19°C.

VOLTAGE - FREQUENCY:

The admitted variation of supply voltage and frequency is established by the norm EN60034-1

Within this tolerance delphi motors provide the rated power reported in the plate.



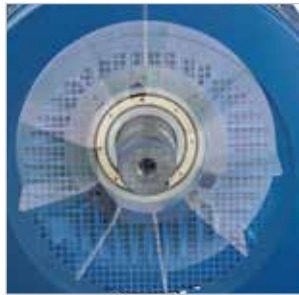
INSULATION:

The copper is impregnated with a double layer of H class insulating enamel to ensure high resistance to electrical, thermal and mechanical stress.

A NOMEX film that wraps entirely around the coil side insulates the copper and iron from one another.

The phases are further isolated by another layer of NOMEX to protect the motors from voltage peaks that usually occur when the motor is controlled by inverter.

In case that motors with more than 75kW are controlled by inverter, we suggest to request the electrically insulated bearing on the non drive end.



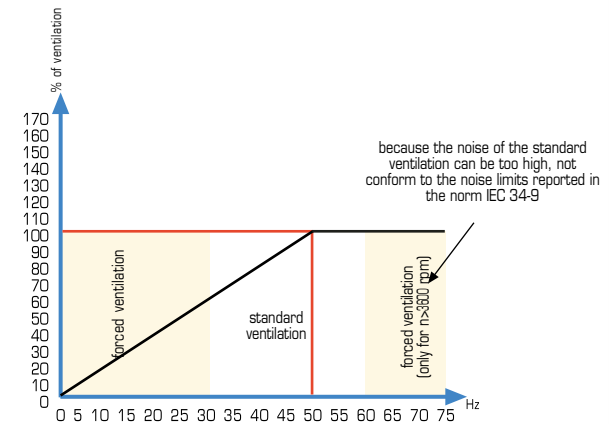
Its purpose is to open the electric circuit between the rotor and the motor frame, thus preventing that the shaft currents go through the bearings and damage their balls surface and roll tracks.

The section "technical data" of this catalogue shows the max operating temperatures according to the Class insulation shown on the plate.

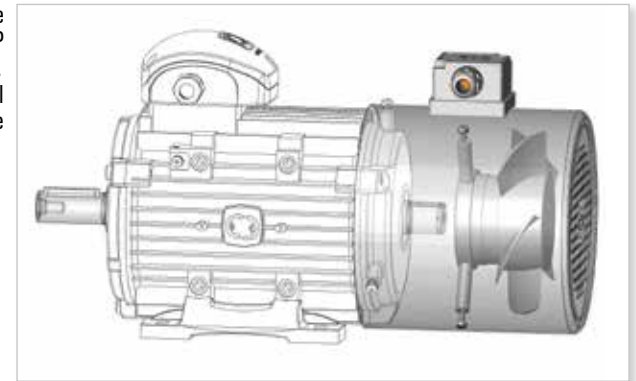
Delphi motors are designed to conserve wide margins against eventual overloads, having a temperature rise that is, at rated power, much lower than the operating temperature limit given by their insulation class. This fact increases considerably the motors life length. Such "ΔT" values are evidenced in the following performance charts. (see further details about temperature rise in the "technical data" section of this catalogue)

ASSISTED POWER COOLING

For application with a power supply at certain frequencies (see following graph), a power cooling system (IC-416) must be used.

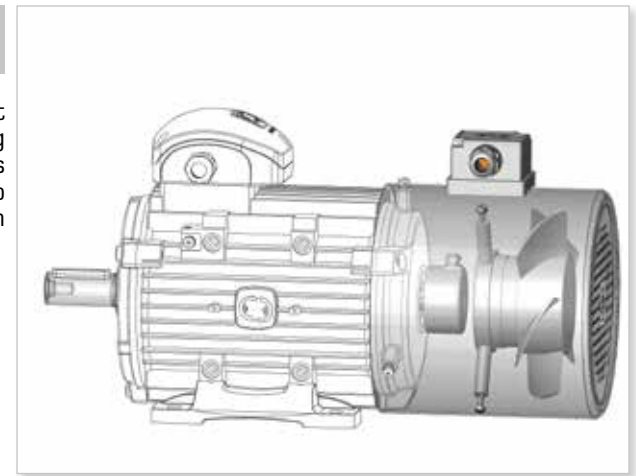


Motive power cooling systems are three-phase 400/50 400/60, IP 55, and with separate terminal box. Upon request, single phase and special voltage power cooling systems are also available.



ENCODER

Motors with encoder or special shaft configurations for encoder mounting are available upon request. In this case, assisted power cooling is also available, supported by brackets on the fan cover



MOTIVE MOTORS PROTECTION

Protections must be chosen based on the specific running conditions, according to standards EN 60204-1

External protections



- Protection against overloads. A thermal cut-out relay, which automatically controls a knife switch.



- Protection against peak currents by magnetic relay that controls an automatic knife switch, or by fuses; these must be set to the locked rotor current.

- If the application requires, protection against excessive speed of the electric motor, for example if the mechanical load may drive the electric motor itself and thereby create a hazardous situation.

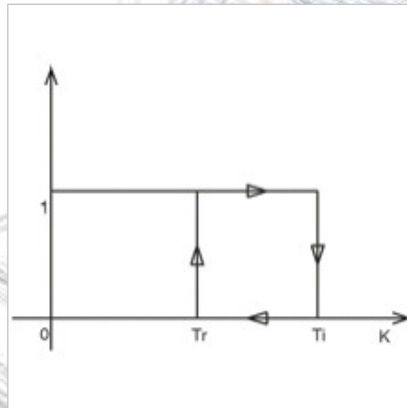
- If special conditions or synchronised operation with other machines or parts of machines require it, protection against power failures or dips by means of a minimum voltage relay that controls an automatic power knife switch.

Inner thermal overload cut-out switches (per CEI 2-3/IEC 34-1)

The electrical protections on the motor power line may not be sufficient to protect against overloads. If the cooling conditions worsen, the motor overheats but the electrical conditions do not change, which inhibits line protections. Installing built-in protections on the windings solves this problem:

● bimetallic device "PTO"

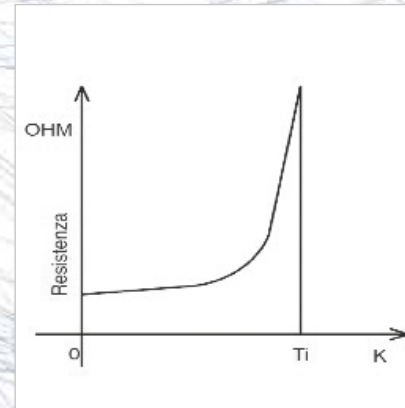
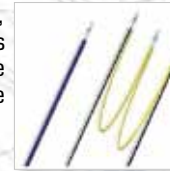
this is a normally-closed electromechanical device that opens when the threshold temperature is reached; it automatically resets when the temperature falls below the threshold level. Bimetallic devices are available with various intervention temperatures and without automatic reset, per EN 60204-1.



Tr= Opening temperature (motor stops)
Ti= Re-closing temperature (motor works again)

● PTC thermistor device

this device promptly, positively adjusts its resistance once the threshold temperature is reached.

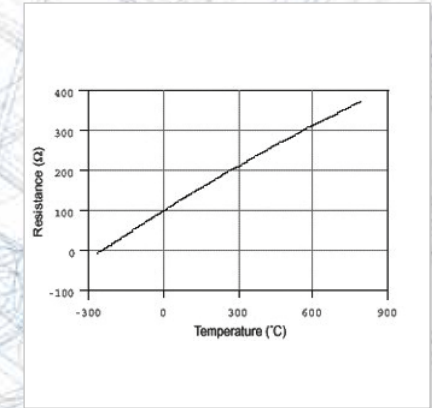


Ti= activating temperature

● PT100 device



this is a device that continuously, increasingly adjusts its resistance according to the temperature. It is useful for constant measuring of the winding temperatures using electronic



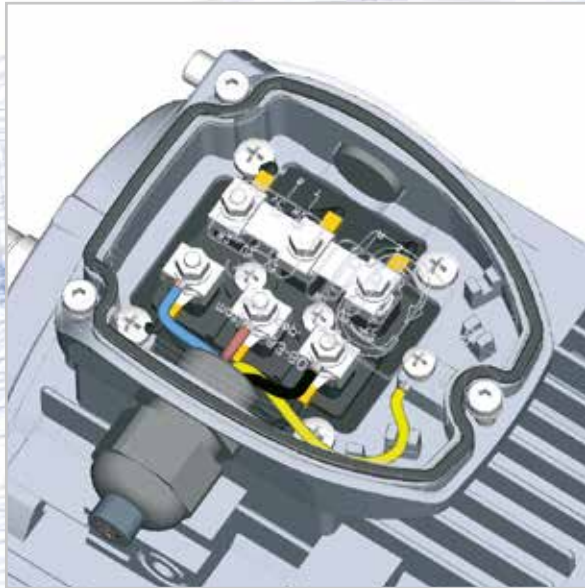
Motors "Delphi Ex - II 3G Ex nA" and all motors from type 160 to type 355L are equipped with 3 PTC thermistors in the winding, with temperature intervention of 120-130°C in Class F motors (standard) (150-160°C in H Class motors, not delphi Ex)

Types 160-400
Cable gland for PTC



WIRING DIAGRAMS

Motive three phase motors can be connected "Star" or "Delta".



STAR CONNECTION

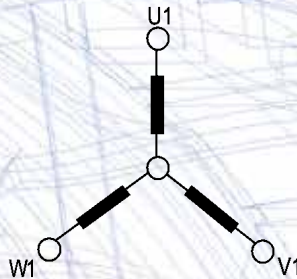
Star connection is obtained by connecting together the terminals W2, U2, V2 and supplying the terminals U1, V1, W1.

The phase current and voltage are respectively:

$$I_{ph} = I_n$$

$$U_{ph} = U_n / \sqrt{3}$$

where I_n is the supply line current and U_n is the supply line voltage of Star connection



the following voltages and frequencies are inside the standard power supply of all three-phase motive motors, under S1 duty service:

Size	Hz	Volts	
56-132	50 ±5%	230	400
		220	380
		240	415
	60 ±5%	260	440
		220	380
		265	460
132-355	50 ±5%	280	480
		400	690
		380	660
	60 ±5%	415	720
		440	760
		380	660
	60 ±5%	460	795
		480	830

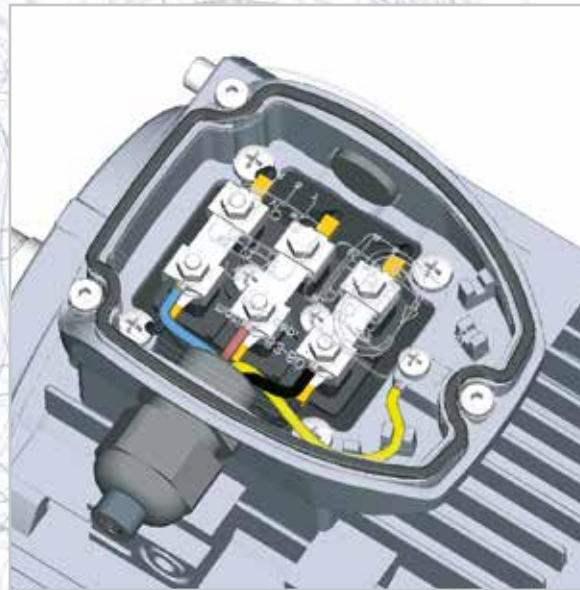
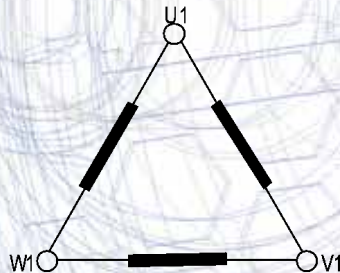
DELTA CONNECTION

Delta connection is obtained by connecting the end of a phase with the beginning of the following one. The phase current I_{ph} and the phase voltage U_{ph} are respectively:

$$I_{ph} = I_n / \sqrt{3}$$

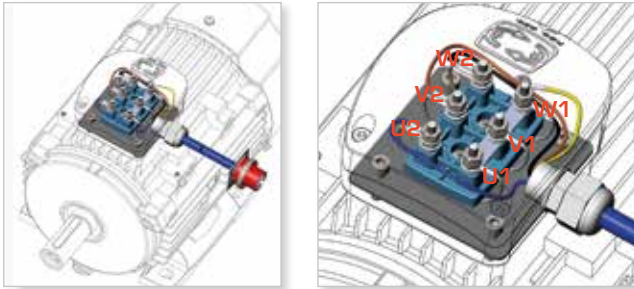
$$U_{ph} = U_n$$

where I_n and U_n are referred to Delta connection.

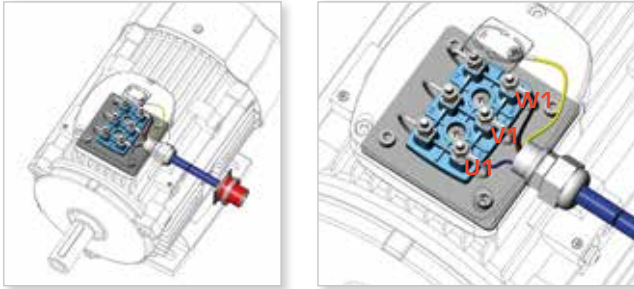


Double polarity motor, single winding (dahlander)

High-speed connection



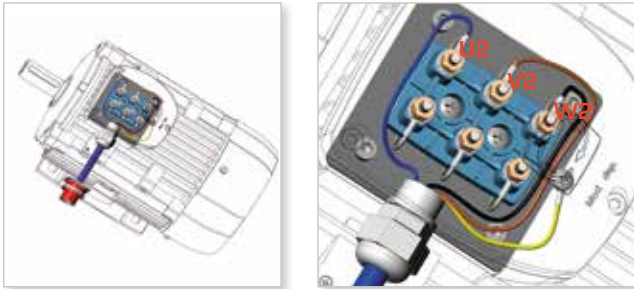
Low-speed connection



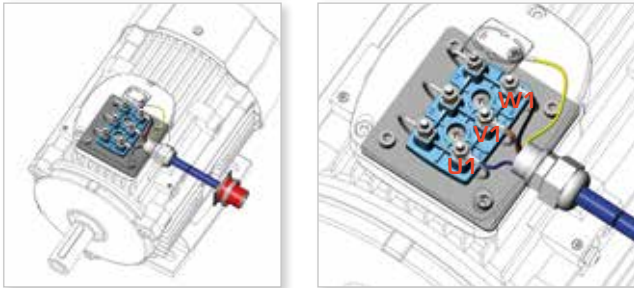
To use the 2 speeds, you must adopt a 6+1 wires cable and connect an external switch

Double polarity motor, with double winding

High-speed connection

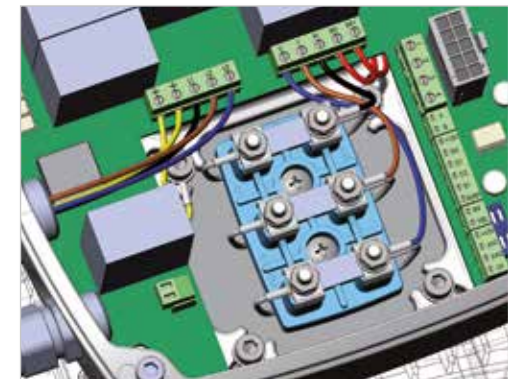
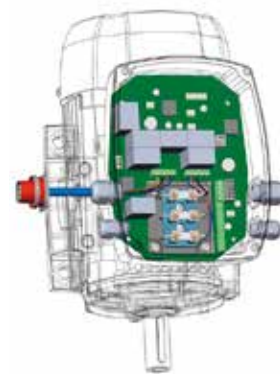
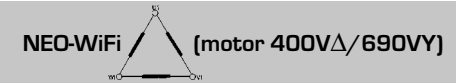
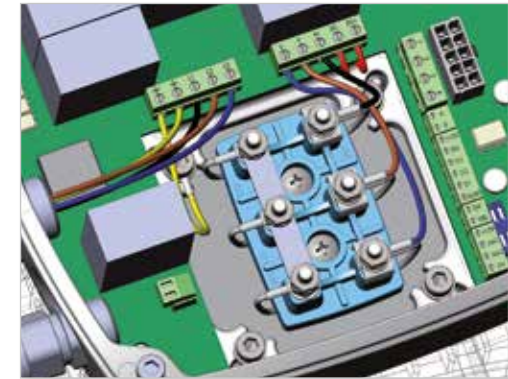
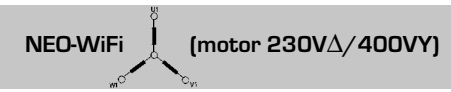
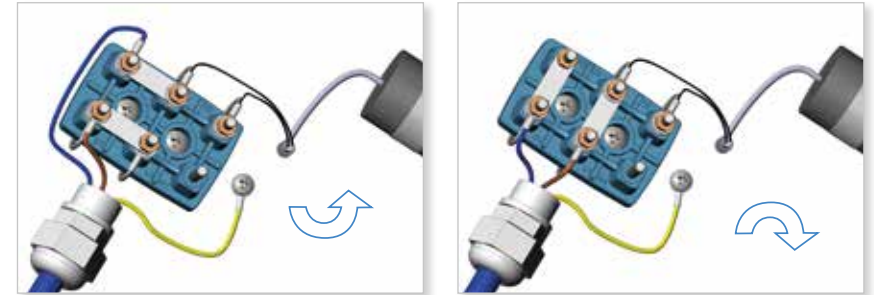


Low-speed connection

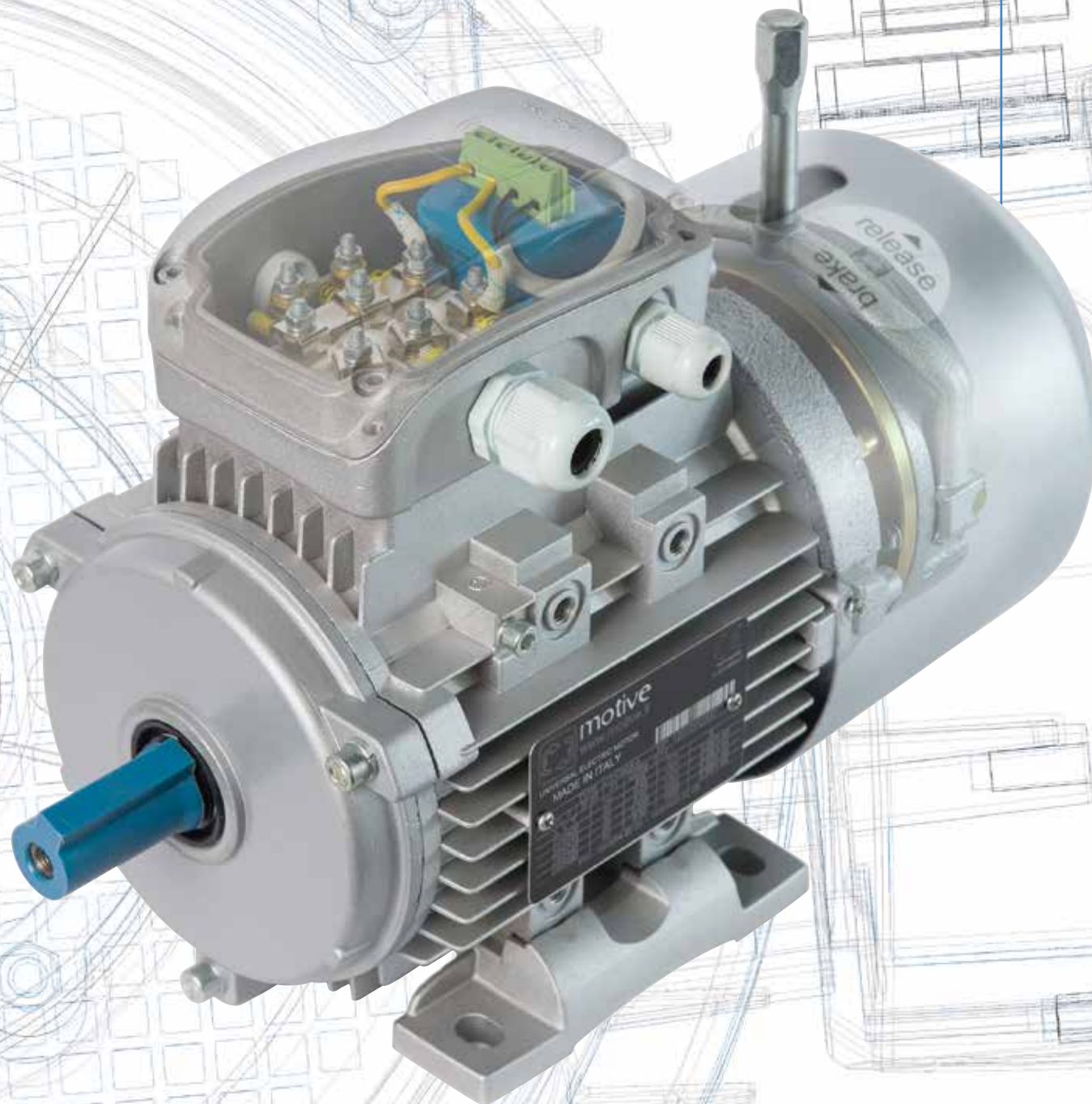


To use the 2 speeds, you must adopt a 6+1 wires cable and connect an external switch

Single phase motors



THREE-PHASE SELF-BRAKING MOTORS SERIES DELPHI AT



DELPHI AT

Delphi ATDC, AT24, ATTD and ATTD24 series self-braking motors use one or 2 spring-pressure brakes, firmly spliced onto a cast iron shield at the back of the motor.

These motors include a series of characteristics normally considered options by other brands, like:
 -The standard hand lever permits to release the brake, making it possible to move manually the shaft,
 -The PTO thermal protectors in the winding are a standard up to size 132. PTC are a standard from size 160 and up

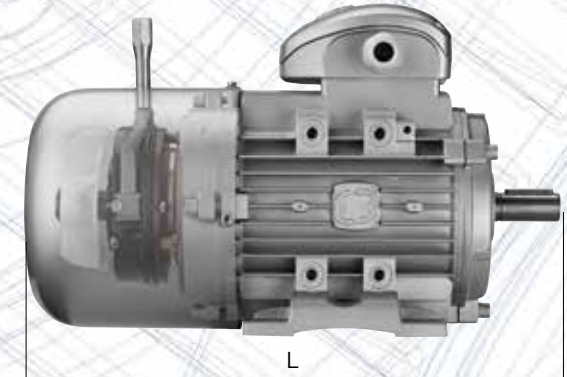
-Easy separate connection of the brake in case that the motor is connected to an inverter.

On ATDC and ATTD, the separate brake power supply is achieved, whenever needed, by connecting directly to the brake terminal board located inside the motor terminal box.

On AT24 and ATTD24, the 24Vdc single or double brakes are designed to be directly connected to an inverter (usually having a 24Vdc plug)

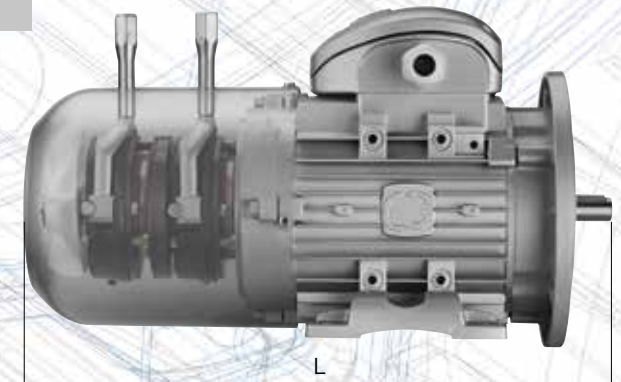
On request, the brakes can be modified to be extremely silent for usage in special environments like theatres

ATDC/AT24



L

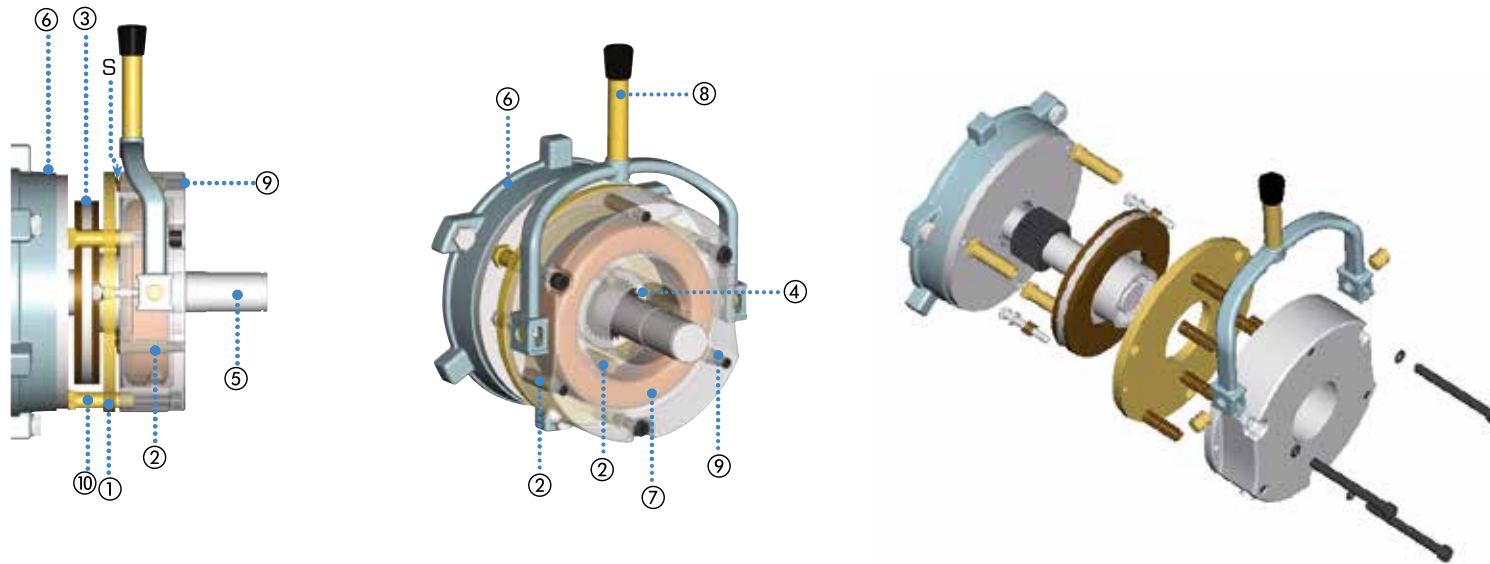
ATTD/ATTD24



L

IEC Type	ATDC			AT24				ATDC AT24	ATTD ATTD24			
	Static max braking torque [Nm]	standard vers. braking time no-load [Sec]	"TA version" braking time no-load [Sec]	input voltage on rectifier [Vac]	output voltage to brake [Vdc]	brake power [W]	Static max braking torque [Nm]	Static min braking torque [Nm]	Braking time no-load [Sec]	brake power [W]	extra Kg on std	extra Kg on std
AT..63	4,5	0,15	<0,05	220-280 [opt. 380-480]	99-126 [opt. 171-216]	20	4,5	4,0	0,06	20	+4	+7,5
AT..71	8,0	0,15	<0,05	220-280 [opt. 380-480]	99-126 [opt. 171-216]	28	4,5	4,0	0,06	20	+5	+9
AT..80	12,5	0,20	<0,05	220-280 [opt. 380-480]	99-126 [opt. 171-216]	30	10,0	9,0	0,09	25	+5,5	+10
AT..90	20,0	0,25	<0,05	220-280 [opt. 380-480]	99-126 [opt. 171-216]	45	16,0	12,0	0,11	45	+6	+11
AT..100	38,0	0,30	<0,05	220-280 [opt. 380-480]	99-126 [opt. 171-216]	60	32,0	28,0	0,14	60	+7	+12,5
AT..112	55,0	0,35	<0,05	380-480	171-216	65	65,0	55,0	0,15	65	+10	+19
AT..132	90,0	0,40	<0,05	380-480	171-216	90	90,0	80,0	0,16	85	+12	+23
AT..160	160,0	0,50	<0,05	380-480	171-216	110	160,0	130,0	0,21	105	+22	+42
AT..180	250,0	0,50	<0,05	380-480	171-216	130					+32	+62
AT..200	420,0	0,50	<0,05	380-480	171-216	140					+40	+77
AT..225	450,0	0,50	<0,05	380-480	171-216	160					+52	+100
AT..250	550,0	0,50	<0,05	380-480	171-216	170					+80	+155
AT..280	900,0	0,50	<0,05	380-480	171-216	360					+106	+209
ATTD/ATTD24	ATTD= ATDCx2					ATTD= ATDCx2	ATTD24= AT24 x 2			ATTD24= AT24 x 2		

ATDC



- ① Mobile armature
 - ② springs
 - ③ Brake disc
 - ④ Driver
 - ⑤ Motor shaft
 - ⑥ Motor flange
 - ⑦ Electromagnet
 - ⑧ Release lever
 - ⑨ Adjuster screws
 - ⑩ Threaded bush
 - ⑪ braking torque setting knob
 - ⑫ ATTD connection plate
- S** Air gap

BRAKE DESCRIPTION

The delphi AT... series brakes are electromagnetic brakes with negative operation, whose braking action is exercised in the absence of power supply. The brakes insulation class is F. The brakes lining is asbestos-free. The rectifier is of relays type, with protection varistors at the entry and the exit. All brake assemblies are protected against corrosion by painting or heat galvanizing and resined winding. The parts most subject to wear are treated in special atmospheres that provide considerable wear resistance to the parts.

BRAKE OPERATION

When the power supply is interrupted, the excitation coil ⑦ is no longer powered and therefore doesn't exert the magnetic force necessary to restrain the mobile armature ①, which, pushed by the pressure springs ②, compresses the brake disc ③ against the motor flange ⑥ on one side and the armature itself on the other, thereby creating a braking action.

ADJUSTMENT

Two different types of adjustment are possible

S air gap adjustment

For proper operation, the air gap S between electromagnet ⑦ and the mobile armature ① must be between the following indicated limits:

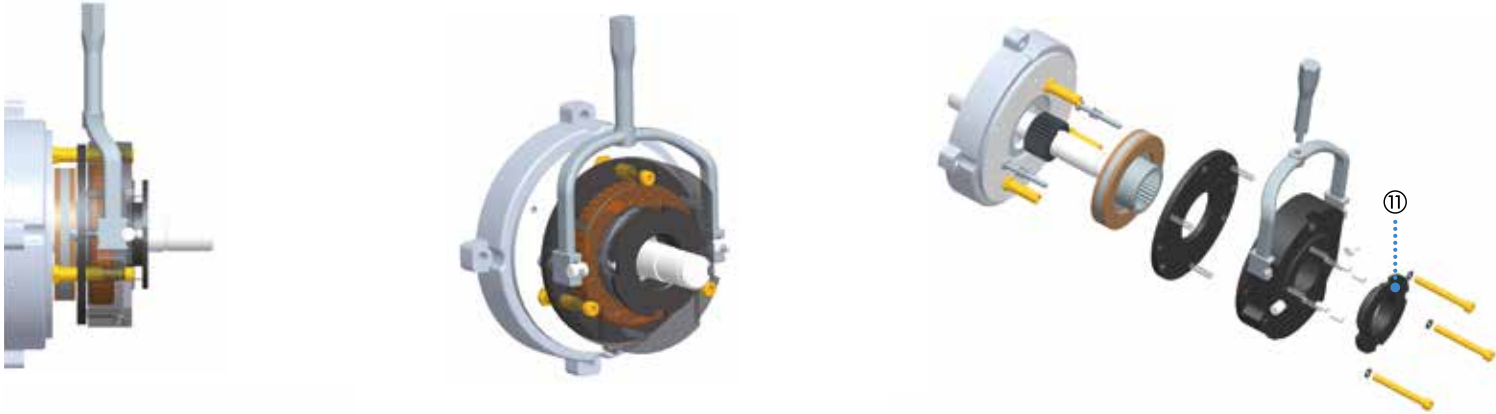
MOTOR TYPE	S AIR GAP (mm)
63-71	0.40-0.50
80-160	0.50-0.60

The adjustment is made by using the threaded bushes ⑩, using a thickness gauge to make sure that the wished air gap is reached.

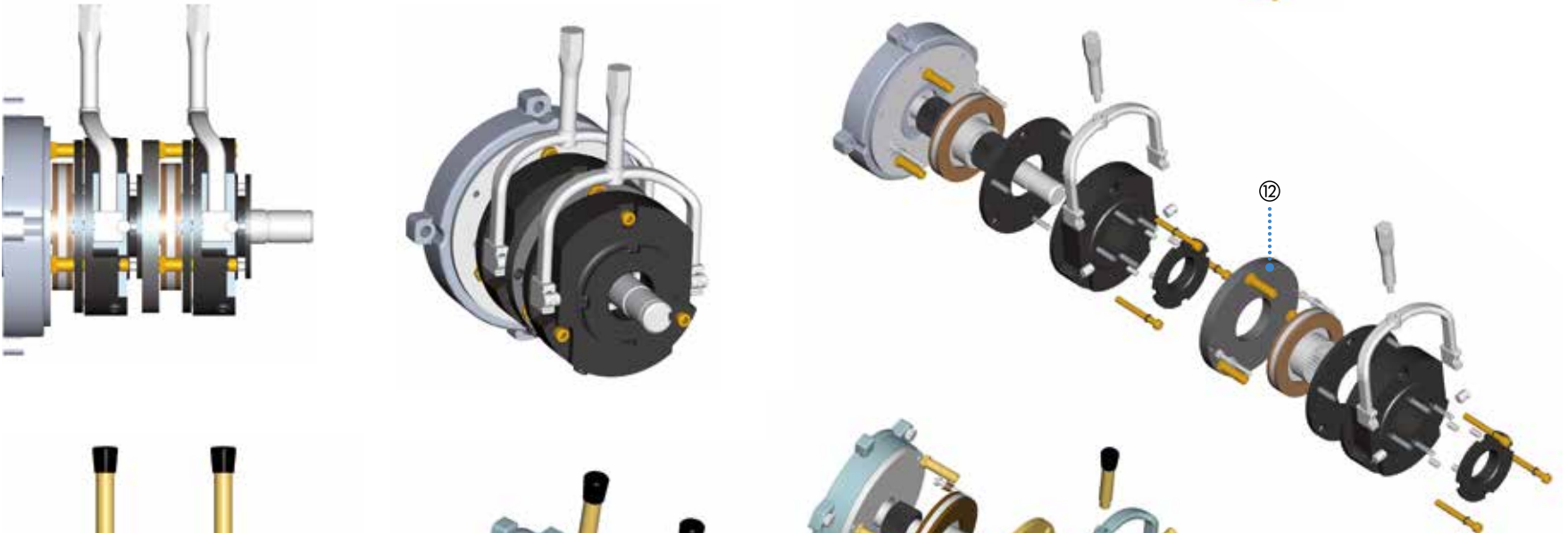
Braking torque adjustment

The braking torque is set to its max level by Motive, but it can be decreased by acting on the adjuster screws ⑨ (ATDC and ATTD motors) or on the knob ⑪ (AT24 and ATTD24).

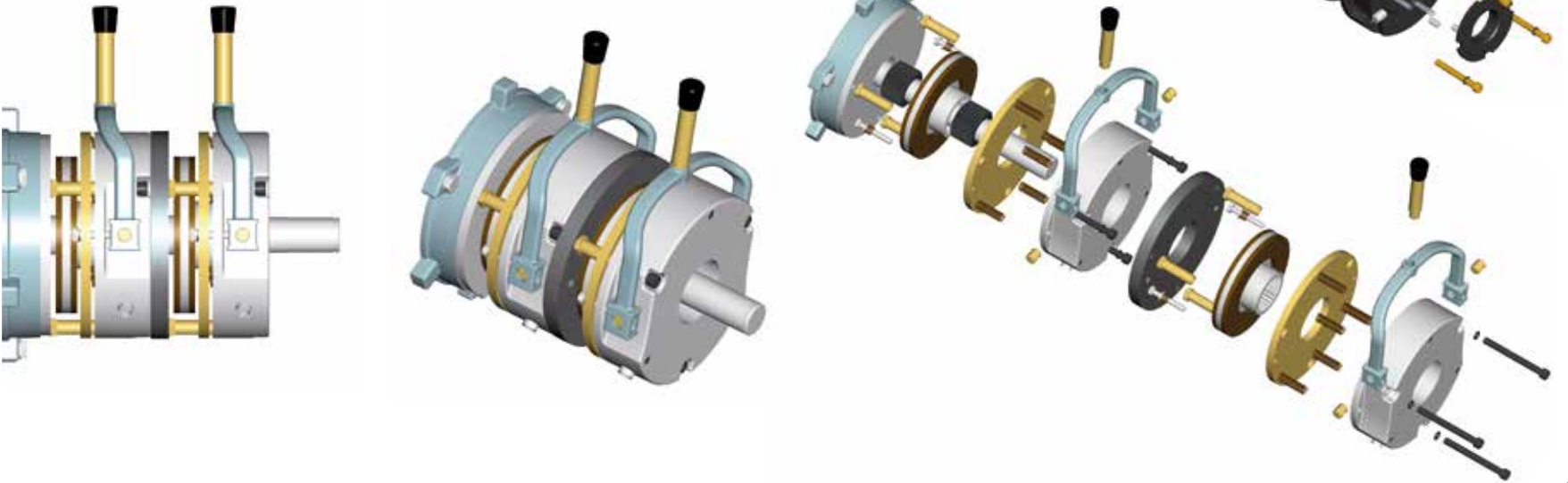
AT24



ATTD24



ATTD

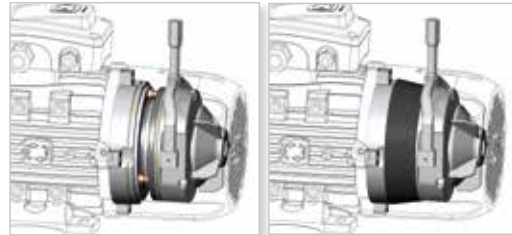


MANUAL RELEASE

Motive brake motors are supplied with the manual release lever in their standard version. If not wished, the lever is like a screw, that can be taken away simply turning it. ATTD and ATTD24 tandem brake motors, from size 180 up to sized 280, cannot have the manual release.

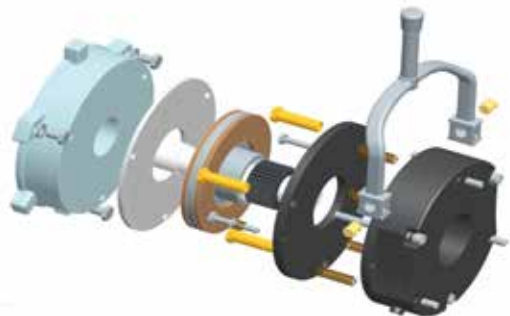


In order to safeguard the braking torque, it is necessary to clean periodically the parts inside the rubber ring seal by the dust created by the disc lining.



STAINLESS STEEL BRAKING SURFACE

When high humidity in the air can rust fastly the contact surface between the brake disc and the cast-iron NDE shield of the motor, you can request to motive to add a stainless steel shield.

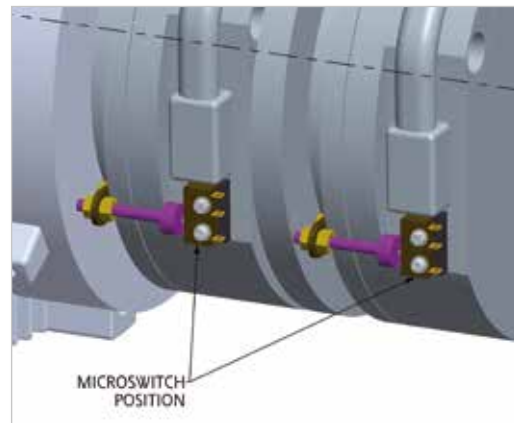


IP

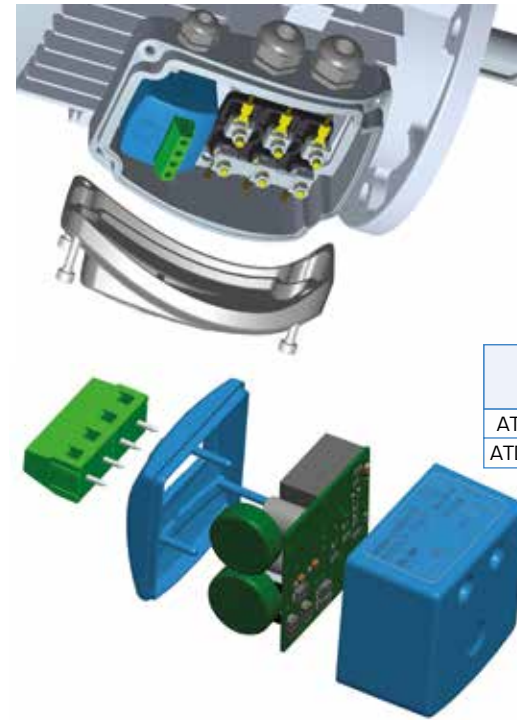
AT.. brakes are IP66 under an electrical point of view, but mechanically, in case of an outdoor use, they should be protected by rust and by disc adhesion effects given by humidity. In such a case, we suggest to use our protective rubber ring seals. This device prevents the exit or ingress of dust, humidity, dirt, etc., out of or into the braking area. It is inserted into the groove on the stator. If your brake doesn't have such a groove, you must order a specifically machined brake for that.

MICRO-SWITCHES TO DETECT BRAKE POSITION

Optional.



POWER SUPPLY



ATDC brakes are DC brakes power supplied by a rectifier installed inside the motor main terminal box.

The following tablechart shows the tensions on the rectifier and the brake of ATDC model

Type	input voltage on rectifier [Vac]	output voltage to brake [Vdc]
ATDC 63-100	220-280	99-126
ATDC 112-280	380-480	171-216

Unless there's a different request of the client, motive supplies ATDC brake motors with the rectifier already connected directly to the main terminal block of the motor (fig. 1, 2, 3 and 4), in order to permit to the motor switching to act at the same time on the brake.

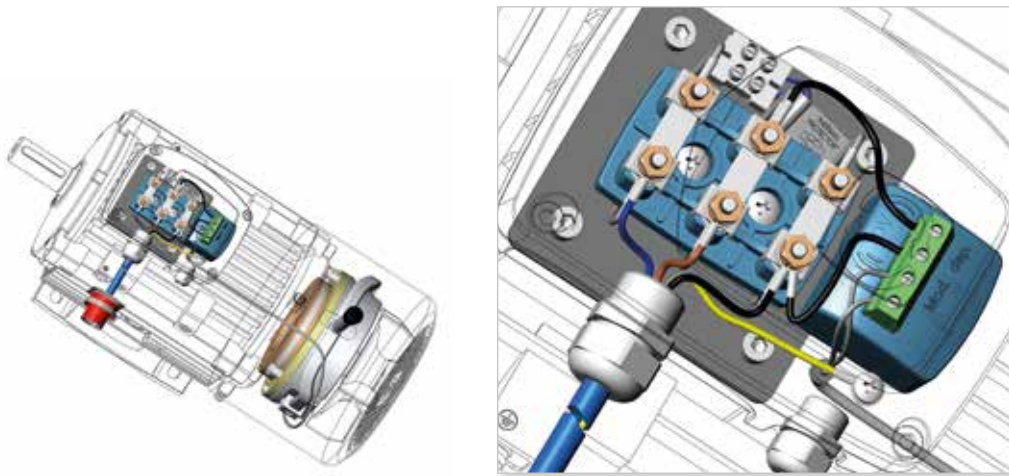
In case that the motor is power supplied by a frequency inverter (fig. 5a and 5b), or at a special voltage*, or at a low tension during the start, or in case that the motor is used to move loads which can have an inertial movement, like lifted weights (such inertial movement can move the motor when the power is switched off, and the motor can act like a generator on the rectifier avoiding the brake locking), disconnect the motor main terminal board from the rectifier, and connect separately the rectifier (ATDC) (fig. 5a, 5b, 6 and 7). TA special rectifier permits to solve the problem of inertial movements with no need for a separate power supply to the rectifier (fig 3 and 4)

This exclusive rectifier offers the following innovations:

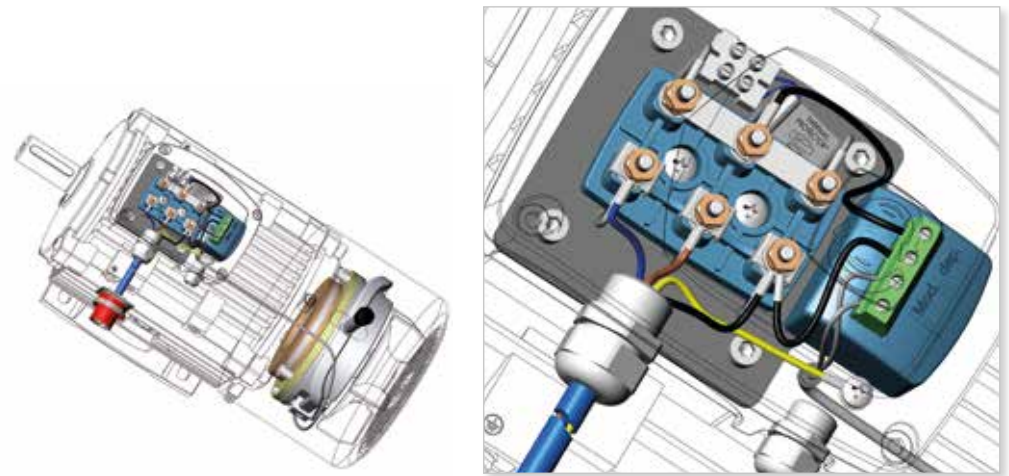
- double semi-wave technology.
- special vibration proof 6 Ampere relays (like the ones used on Ducati race motorbikes).
- electric arcs ultra resistant contacts in silver alloy.
- relays system instead of normal mosfets system, thus more resistant against tension peaks, even if impulsive.
- an in-built current reading system which controls the current sinusoid and the relay commutation time.

What's the advantage? Rectifier is normally the "brain" and the fragile point of any dc brake motor. This rectifier is stronger against disturbs coming from power line, much stronger than what required by European EMC rules for industrial environment; they are more resistant against vibrations; and they are faster.

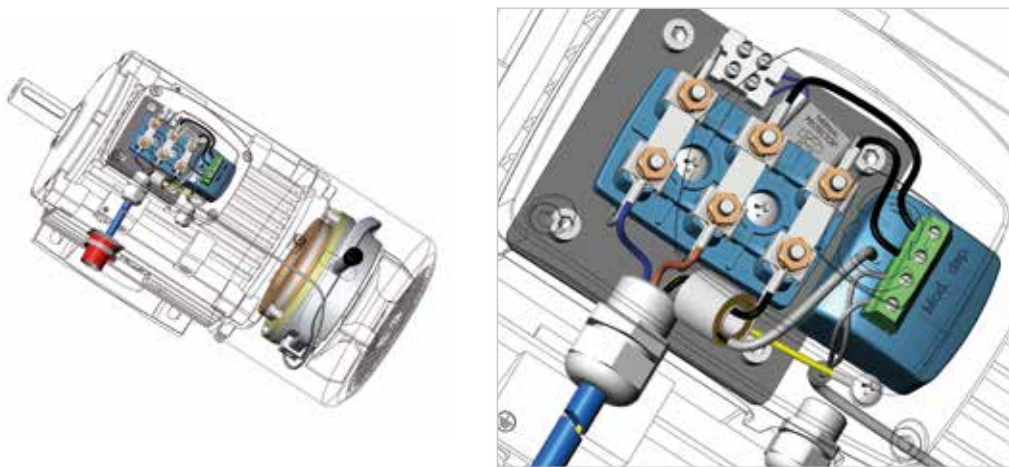
ATDC 112-280 Δ - 400Vac/180Vdc rectifier (III.1)



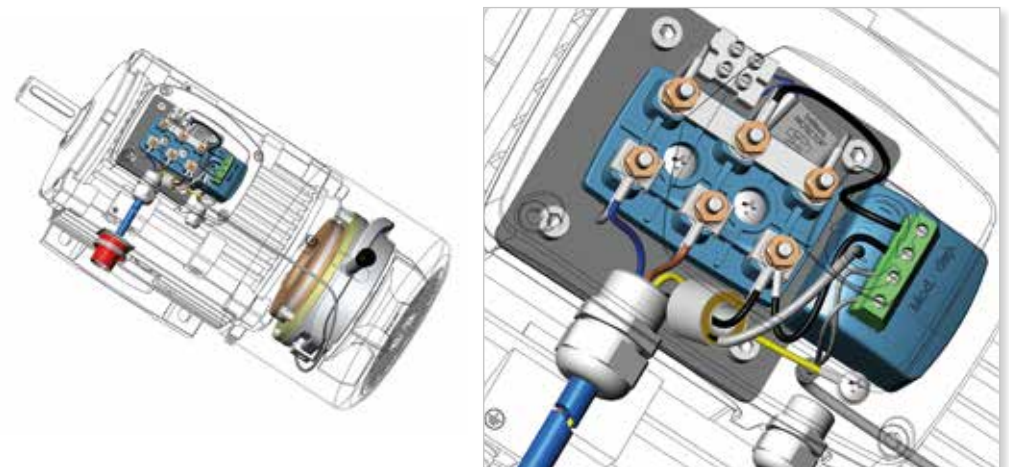
ATDC 63-100 Δ - 230Vac/104Vdc rectifier (III.2)




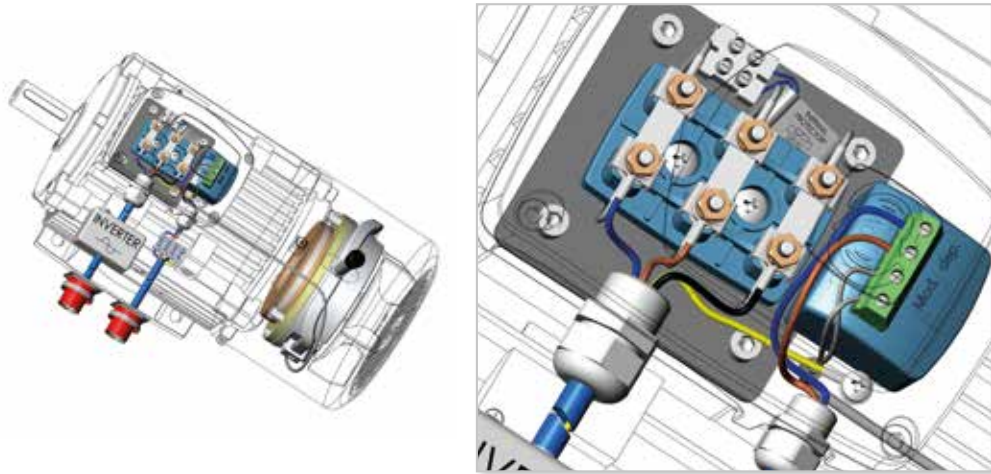
ATDC 112-280 Δ 400Vac/180Vdc TA rectifier (III.3)



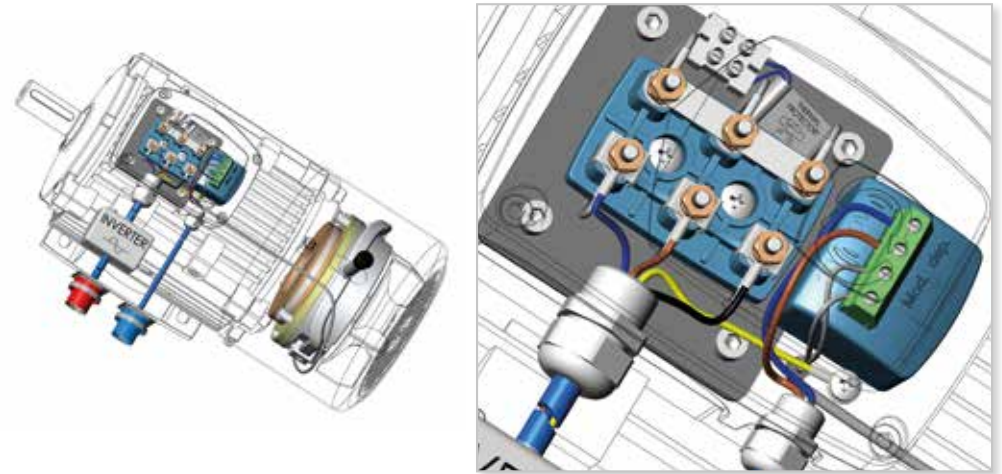
ATDC 63-100 Δ + 230Vac/104Vdc TA rectifier (III.4)




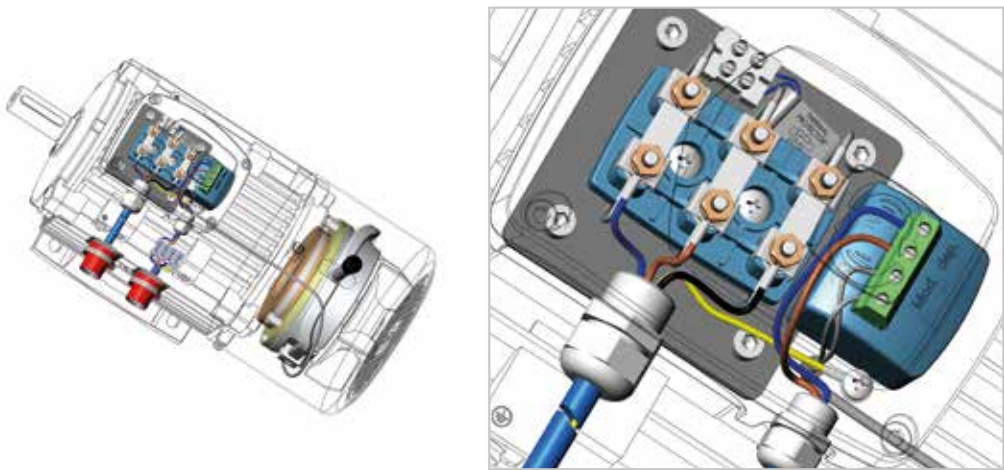
ATDC 112-280  [separate 400Vac/180Vdc rectifier] + inverter (Ill. 5)



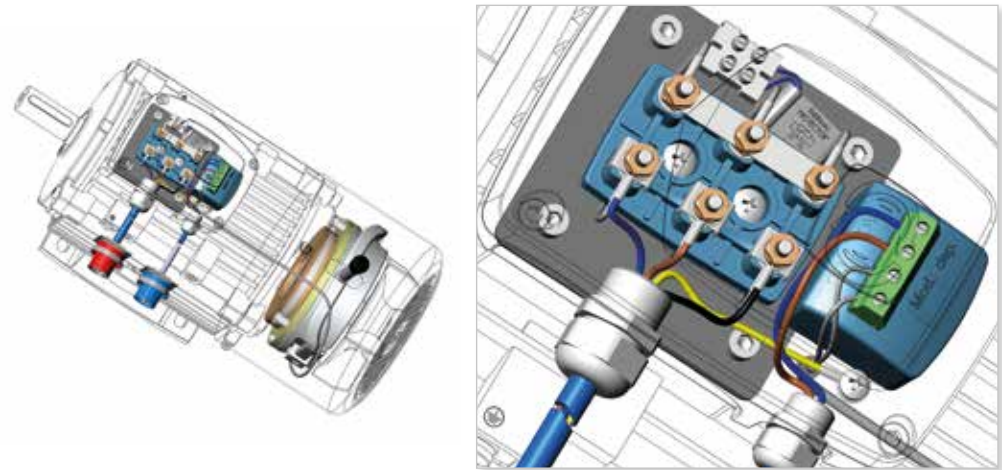
ATDC 63-100  [separate rectifier 230Vac/104Vdc] + inverter (Ill. 5b)



















ATDC 112-280  + separate 400Vac/180Vdc rectifier connection (Ill. 6)



ATDC 63-100  + separate 230/104Vdc rectifier connection (Ill. 7)



MOTOR CONFIGURATIONS AND INSTALLATION POSITIONS (IEC 34-7)

MOTORS WITH FEET B3		FLANGE-MOUNTED MOTORS B5	FLANGE-MOUNTED MOTORS B14
 IM1051 (IM B6)	 IM1001 (IM B3)	 IM3001 (IM B5)	 IM3601 (IM B14)
 IM1061 (IM B7)	 IM1011 (IM V5)	 IM3011 (IM V1)	 IM3611 (IM V18)
 IM1071 (IM B8)	 IM1031 (IM V6)	 IM3031 (IM V3)	 IM3631 (IM V19)
B3/B5  IM2001 (IM B35)	B3/B14  IM2101 (IM B34)	V1/V5  IM2011 (IM V15)	V3/V6  IM2031 (IM V36)

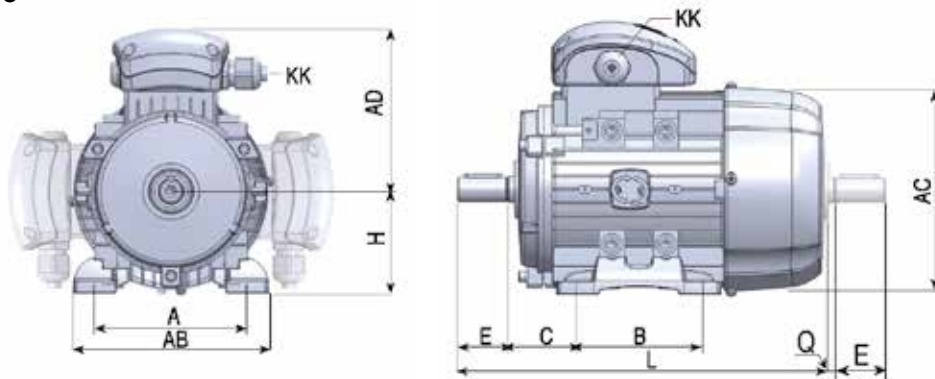


TYPE	POLES	SV	SV	ATDC	ATDC+SV	ATTD	ATTD+SV
		IE2	IE3	AT24	AT24+SV	ATTD24	ATTD24+SV
		L	L	L	L	L	L
56	2-8	-	-	-	-	-	-
63	2-8	301	-	261	331	321	351
71	2-8	341	-	295	375	365	400
80	2-8	388	-	340	392	417	421
90S	2-8	420	440	385	426	465	471
90L	2-8	445	465	410	451	490	496
100	2-8	483	503	450	495	488	500
112M	2-8	525	545	475	565	563	603
132S	2-8	590	610	550	620	640	670
132M	2-8	625	645	590	655	677	647
160M	2-8	765	815	720	819	820	929
160L	2-8	810	860	755	862	855	972
180M	2-8	805	855	810	954	957	1104
180L	2-8	845	895	850	992	997	1142
200L	2-8	960	1010	890	1013	1050	1178
225S	2-8	955	955	935	1090	1115	1125
225M	2	955	955	935	1090	1115	1125
225M	4-8	985	985	965	1120	1145	1255
250M	2	1045	1045	1075	1211	1285	1466
250M	4-8	1045	1045	1075	1211	1285	1466
280S	2	1105	1105	1175	1274	1355	1444
280S	4-8	1105	1105	1175	1274	1355	1444
280M	2	1160	1160	1230	1329	1410	1499
280M	4-8	1160	1160	1230	1329	1410	1499
315S	2	1400	1400				
315S	4-8	1430	1430				
315M	2	1500	1500				
315M	4-8	1530	1530				
315L	2	1500	1500				
315L	4-8	1530	1530				
355M	2	1740	1740				
355M	4-8	1770	1770				
355L	2	1740	1740				
355L	4-8	1770	1770				

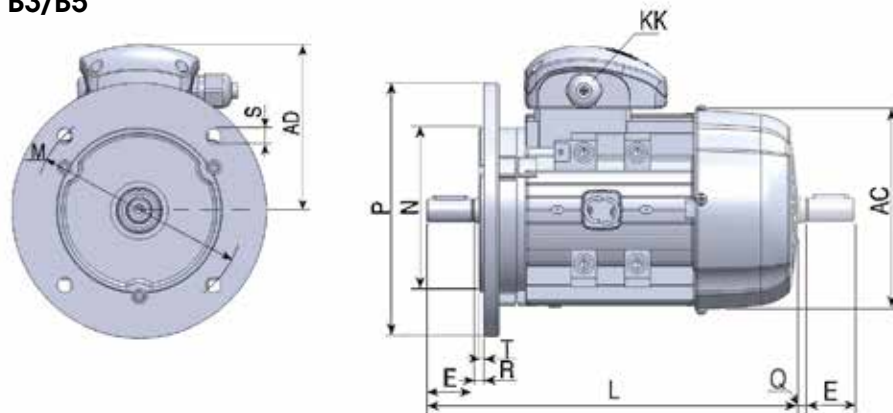


you can download 2D and 3D drawings from www.motive.it

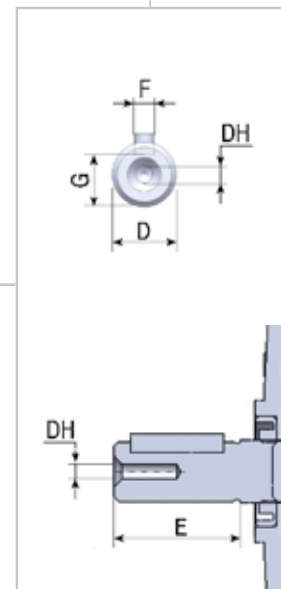
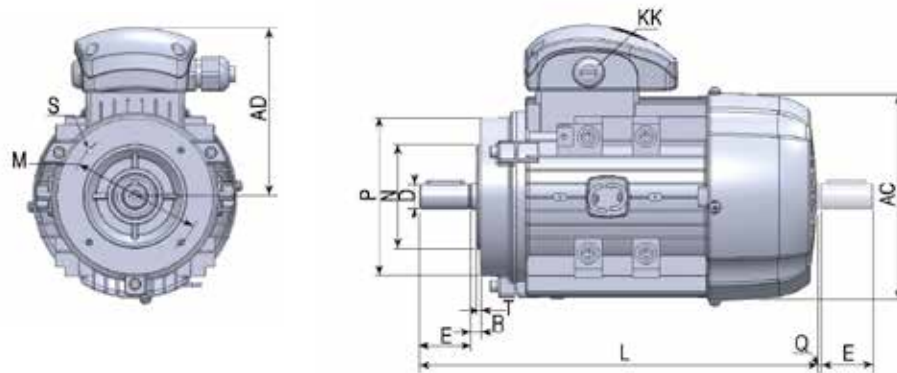
B3



B5, B3/B5



B14, B5R/B14B



The general electrical specifications are listed in the performance charts that follow. To understand their contents, the following general definitions are provided.

Rated Power:
it is the mechanical power measured at the shaft expressed, according to the latest indications of international Standards Committees, in Watts or Kwatts. However, in the engineering sector it is still common to refer to power in terms of HP

Rated Voltage:
the voltage to be applied to the motor terminals in accordance with the specifications in the following tables

Frequency:
All electrical data in this catalogue refer to three-phase wound motors at 50 Hz. These may be connected to 60 Hz, taking into account the multiplier coefficients in the table below

Rated Current:
"In" is the Rated Current, expressed in Ampere, absorbed by the motor when supplied at Rated Voltage Vn (V) and giving the Rated Power Pn (W) and it is obtained by the formula

$$I_n = \frac{P_n}{\sqrt{3} \cdot V_n \cdot \eta \cdot \cos\varphi} \text{ (A)}$$

In the following tables, the rated currents are referred to a Voltage supply of 400V. For other voltage supplies the absorbed rated current can be considered inversely proportional to the voltage supply.
EX:

Volt	230	380	400	440	690
In	1,74	1,05	1,00	0,91	0,64

Rated torque:
Cn is expressed in Nm, and it corresponds to the rated power and rated rpm. It is given by the multiplication of the force for the arm (distance) and it is measured in Nm because the force is expressed in Newton and the distance in metres. The rated torque value is obtained by the formula

$$C_n \text{ (Nm)} = P_n \times 9550 / \text{rpm}$$

Pn= Rated power in KW
rpm= rated rotation speed

Efficiency:
η is expressed in % and it is given by the relation between the output Power and the addition of output Power and the electric losses of the motor, that is the input power absorbed by the motor. The electric motors losses are mainly of two kinds: for joule effect (rotor and stator) and iron losses. The latest cause essentially heat. An higher efficiency means energy savings, lower heating, longer life of insulating materials.

The smaller a motor is, the more the presence of a double lip oil seal as the ones used on the drive end of delphi flanged motors (B5 or B14) may affect, following the friction generated, performance. The motors B3 up to size 132, however, have V-rings with an almost non existent level of friction. For simplicity, the following performance tables indicate the levels of absorption and performance measured on B14 motors for size 56 and B3 motors for size 63 and above.

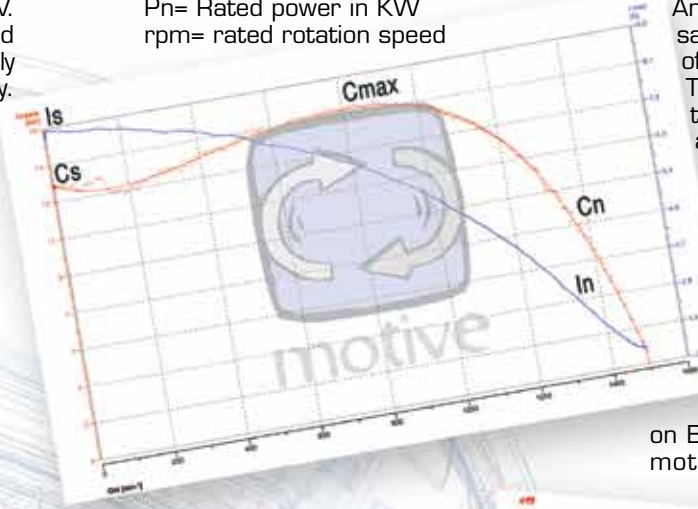
rated voltage at 50Hz	Volt at 60Hz	rated power W	In (A)	Cn (Nm)	rpm	Is (A)	Cs (Nm)	Cmax (Nm)
230 ± 10%	230 ± 5%	1	1	0,83	1,2	0,83	0,83	0,83
230 ± 10%	230 ± 10%	1	0,95	0,83	1,2	0,83	0,83	0,83
230 ± 10%	240 ± 5%	1,05	1	0,87	1,2	0,87	0,87	0,87
400 ± 10%	380 ± 5%	1	1	0,83	1,2	0,83	0,83	0,83
400 ± 10%	400 ± 10%	1	0,95	0,83	1,2	0,83	0,83	0,83
400 ± 10%	415 ± 10%	1,05	1	0,87	1,2	0,87	0,87	0,87
400 ± 10%	440 ± 10%	1,10	1	0,90	1,2	0,93	0,93	0,93
400 ± 10%	460 ± 5%	1,15	1	0,96	1,2	0,96	0,96	0,96
400 ± 10%	480 ± 5%	1,20	1	1	1,2	1	1	1

for further information, see chapter "wiring diagrams" at page 12

Synchronous speed:
is expressed in rpm and it is obtained by the formula
 $f = 120/p$
f= supply frequency Hz
p= number of poles pairs

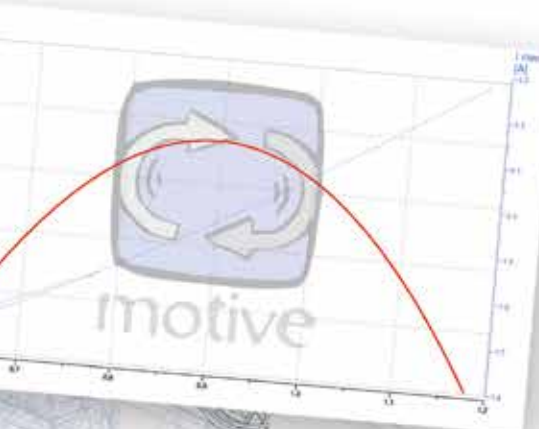
Motive motors can face also temporary overloads, with Current increases of 1.5 times the rated current for at least 2 minutes.

Starting current (or locked rotor current):
(you see diagram)



Starting torque (or locked rotor torque):
Cs is the torque that the motor can provide with the rotor at a standstill and the rated power supply.

Maximum torque:
Cmax is the maximum torque developed by the motor at the rated power supply, at a certain speed. It represents also the value of the resistant torque after which the motor stops. In the following performance charts, it is indicated the relation between maximum torque and rated torque and maximum torque



Power factor or cosφ:
it represents the coseno of the voltage and current gap angle.

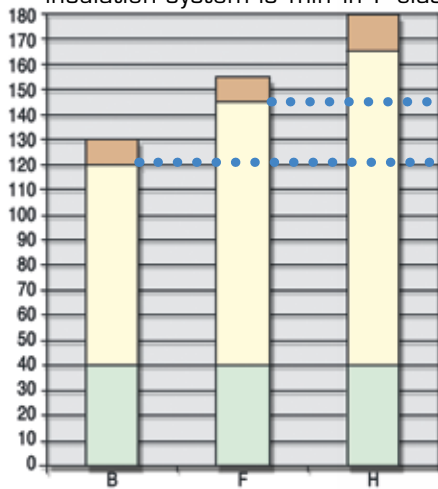
TECHNICAL DATA

temperature rise ΔT :

The temperature rise " ΔT " is the change in temperature of the entire winding of the motor, including the wire placed deep inside the stator slots, when it is being operated at full load.

For example: if a motor is located in a room with a temperature of 40°C, and then is started and operated continuously at the rated power, the winding temperature would rise from 40°C to a higher temperature. The difference between its starting temperature and the final inner elevated temperature, is the ΔT . Almost all our motors are designed to offer a temperature rise of B class or even lower, while their insulation system is min in F class.

Class	amb T (°C)	ΔT (°C)	hot spot allowance (°C)	Tmax (°C)
A	40	60	5	105
E	40	75	5	120
B	40	80	5	130
F	40	105	10	155
H	40	125	15	180



example of overload capability (=life bonus) of an F class motor, with B class temperature rise

hot spot allowance
 ΔT
T. amb.

This extra margin gives the motor a "life bonus". As a rule of thumb, insulation life will be doubled for each 10 degrees of unused insulation temperature capability.

The most common method of measuring the temperature rise of a motor is based on the differences between the cold and hot ohmic resistance of the winding.

The formula is:

$$\Delta T [^{\circ}\text{C}] = (R2-R1)/R1 * (234,5+T1)-(T2-T1) \text{ Where:}$$

R1 = Cold winding resistance in Ohms (just before that the test begins)

R2= Hot winding resistance in Ohms (when the motor has reached its thermal equilibrium)

T1= ambient temperature in °C when test begins

T2= ambient temperature in °C when test is stopped

To change ΔT from Centigrade to Fahrenheit:

$$^{\circ}\text{C} (\Delta T) \times 1,8$$

Note: The motor surface temperature will never exceed the internal temperature of the motor, and will depend upon the design and cooling arrangements.

Noise:

The noise is expressed in dB(A). The measures must be taken in accordance with the standard ISO 1680-2, in order to find the Sound Power level LwA measured at 1m of distance from the perimeter of the machine.

EN 60034-9 standard describes the acoustic Power limits to be respected, indicating the maximum sound power level **LwA**. The noise values indicated in the performance charts that follow are referred to a no-load motor working, supplied at 50Hz and with a tolerance of +3 dB(A).

The moment of inertia can be calculated in this way:

$$J = [1/2] \times M \times (R^2)$$

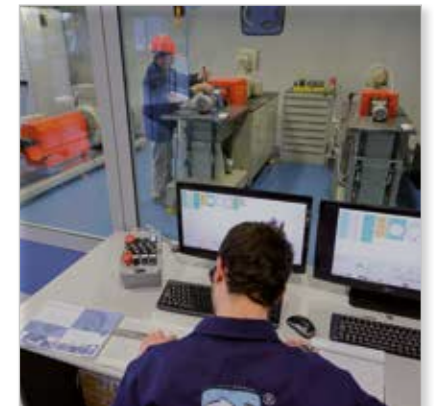
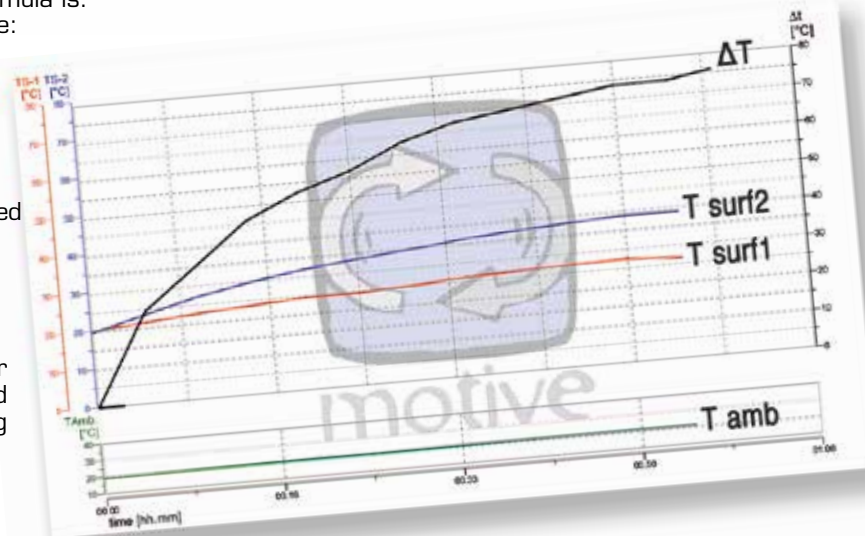
Where M [Kg] is the rotation mass, while R [m] is the ray of the volume at cylindrical symmetry.

TOLERANCES

The data of each motor are specified in this catalogue like requested by the norm IEC 34-1. This describes, in particular, the following tolerances:

Efficiency (Output Power input Power)	-15% di (1- η)
Power factor	1 / 6 of (1- $\cos\phi$) min. 0.02 max 0.07
Locked rotor torque	-15% of the guaranteed torque +25% of the guaranteed torque
Maximum torque	-10% -of the guaranteed torque, if torque is not less than 1,5- 1,6 the rated torque
Noise	+3dB
ΔT	+10°C

The test reports on which the following tables are based can be downloaded from the website www.motive.it





2 Poles

IE2, high efficiency class IE 60034-30

(suitable for variable speed drive duty)

data at 400V 50Hz

KW	HP	Type	rpm	In (A)	Is (A)	Is / In	Cn (Nm)	Cs (Nm)	Cs / Cn	Cmax (Nm)	Cmax / Cn	η %			min IE2	Pwr. Fact.cosφ			ΔT (°C)	LwA (dB)	J Kg·m ²	Kg
												100%	75%	50%		100%	75%	50%				
0,13	0,18	56B-2	2635	0,36	1,06	3,0	0,47	0,95	2,0	0,94	2,0	65,5	65,3	63,0	-	0,806	0,639	0,500	15	60	0,00023	3,6
0,18	0,25	63A-2	2808	0,47	2,03	4,3	0,61	1,60	2,6	1,68	2,7	71,8	70,8	67,0	-	0,766	0,680	0,564	27	61	0,00031	4,5
0,25	0,35	63B-2	2780	0,63	2,81	4,5	0,86	2,30	2,7	2,40	2,8	74,6	70,9	65,0	-	0,770	0,540	0,450	55	61	0,00060	4,7
0,37	0,5	63C-2	2791	0,93	4,13	4,5	1,27	3,60	2,8	3,67	2,9	76,4	76,3	72,8	-	0,755	0,650	0,505	51	61	0,00075	5,7
0,37	0,5	71A-2	2820	0,94	4,33	4,6	1,25	2,90	2,3	3,53	2,8	74,0	73,7	69,1	-	0,770	0,670	0,525	43	64	0,00080	6,0
0,55	0,75	71B-2	2844	1,27	6,94	5,5	1,85	5,60	3,0	5,56	3,0	82,1	83,6	82,0	-	0,760	0,680	0,520	51	64	0,00090	6,3
0,75	1	71C-2	2819	1,69	9,06	5,4	2,54	7,70	3,0	7,72	3,0	79,7	80,5	78,8	77,4	0,806	0,700	0,581	61	64	0,00110	7,3
0,75	1	80A-2	2890	1,76	10,64	6,1	2,48	5,90	2,4	7,80	3,1	80,0	79,0	75,2	77,4	0,770	0,700	0,559	42	67	0,00132	10,0
1,1	1,5	80B-2	2875	2,36	14,18	6,0	3,65	16,60	4,5	11,70	3,2	83,8	84,8	84,0	79,6	0,803	0,730	0,610	48	67	0,00154	11,0
1,5	2	80C-2	2876	3,17	19,72	6,0	4,98	22,80	2,5	13,45	2,7	82,5	82,6	80,1	81,3	0,828	0,760	0,636	54	67	0,00242	12,5
1,5	2	90S-2	2864	3,17	18,62	5,9	5,00	12,30	2,5	15,32	3,1	82,1	82,1	79,7	81,3	0,833	0,760	0,640	62	72	0,00319	13,0
2,2	3	90L-2	2859	4,51	28,31	6,3	7,35	22,30	3,0	23,16	3,2	83,6	85,0	83,9	83,2	0,843	0,780	0,660	70	72	0,00605	14,0
3	4	100L-2	2882	5,94	38,10	6,4	9,94	23,70	2,4	19,75	2,0	84,7	85,4	83,0	84,6	0,860	0,813	0,704	78	76	0,01199	25,0
4	5,5	100LB-2	2863	7,61	47,90	6,3	13,34	34,00	2,5	40,23	3,0	85,9	87,3	86,6	85,8	0,883	0,840	0,757	80	76	0,01210	27,0
4	5,5	112M-2	2887	7,49	46,28	6,2	13,23	28,70	2,2	41,00	3,1	85,8	86,8	85,9	85,8	0,899	0,860	0,768	72	77	0,01386	28,0
5,5	7,5	112MB-2	2883	9,85	67,11	6,8	18,22	45,40	2,5	53,64	2,9	87,1	89,1	89,0	87,0	0,925	0,900	0,817	98	77	0,02068	34,0
5,5	7,5	132SA-2	2908	10,21	67,42	6,6	18,06	35,80	2,0	54,18	3,0	87,2	88,4	87,0	87,0	0,892	0,838	0,764	74	80	0,02750	40,0
7,5	10	132SB-2	2897	13,50	91,05	6,7	24,72	52,40	2,1	73,09	3,0	88,2	89,2	88,8	88,1	0,909	0,871	0,803	89	80	0,03300	45,5
9,2	12,5	132MA-2	2906	16,16	126,72	7,8	30,23	77,40	2,6	90,70	3,0	89,3	90,0	89,9	88,8	0,920	0,900	0,870	72	81	0,03740	53,0
11	15	132MB-2	2895	19,03	146,56	7,7	36,29	90,72	2,5	108,86	3,0	89,5	90,4	89,9	89,4	0,932	0,916	0,886	91	81	0,03960	55,0
11	15	160MA-2	2932	19,82	127,63	6,4	35,83	78,40	2,2	56,10	1,6	89,5	89,3	87,3	89,4	0,895	0,870	0,810	56	86	0,04147	110,0
15	20	160MB-2	2925	26,91	151,67	5,6	48,97	111,20	2,3	75,73	1,5	90,4	90,5	88,3	90,3	0,890	0,853	0,794	91	86	0,05489	120,0
18,5	25	160L-2	2928	32,46	210,47	6,5	60,34	136,40	2,3	65,93	1,1	91,1	91,5	89,8	90,9	0,903	0,876	0,826	95	86	0,06050	135,0
22	30	180M-2	2959	39,26	278,51	7,1	71,00	174,50	2,5	220,80	3,1	91,4	90,8	88,4	91,3	0,885	0,860	0,804	60	89	0,08250	165,0
30	40	200LA-2	2959	52,77	332,71	6,3	96,82	245,00	2,5	309,83	3,2	92,2	93,2	89,5	92,0	0,890	0,871	0,811	63	92	0,13640	217,0
37	50	200LB-2	2949	64,06	391,35	6,1	119,82	260,00	2,2	330,00	2,8	92,5	92,3	89,0	92,5	0,901	0,888	0,841	40	92	0,15290	243,0
45	60	225M-2	2963	78,28	472,34	6,0	145,04	320,00	2,2	380,00	2,6	93,5	93,3	90,2	92,9	0,887	0,865	0,804	69	92	0,25630	320,0
55	75	250M-2	2981	95,63	545,37	5,7	176,20	352,40	2,0	475,74	2,7	93,5	91,6	87,5	93,2	0,888	0,870	0,823	45	93	0,34320	390,0
75	100	280S-2	2970	127,69	614,63	4,8	241,16	409,97	1,7	482,32	2,0	94,3	92,4	88,3	93,8	0,899	0,895	0,874	55	94	0,63690	540,0
90	125	280M-2	2974	153,09	796,95	5,2	289,00	520,21	1,8	693,61	2,4	94,2	94,1	92,1	94,1	0,901	0,895	0,858	60	94	0,74250	590,0
110	150	315S-2	2980	185,05	1313,83	7,1	352,52	634,53	1,8	775,54	2,2	94,4	93,8	92,0	94,3	0,909	0,903	0,840	80	96	1,29800	880,0
132	180	315MA-2	2980	218,75	1553,14	7,1	423,02	761,44	1,8	930,64	2,2	95,0	94,4	93,0	94,6	0,917	0,912	0,903	75	96	2,00200	1000,0
160	215	315LA-2	2980	262,63	1864,69	7,1	512,75	922,95	1,8	1128,05	2,2	95,0	94,4	92,9	94,8	0,926	0,913	0,858	75	99	2,28800	1055,0
200	270	315LB-2	2980	334,84	2377,36	7,1	640,94	1153,69	1,8	1410,07	2,2	95,6	95,1	93,9	95,0	0,902	0,889	0,845	80	99	2,61800	1110,0
250	335	355M-2	2985	410,72	2916,11	7,1	799,83	1279,73	1,6	1759,63	2,2	95,6	95,1	93,8	95,0	0,919	0,908	0,878	70	103	3,30000	1900,0
315	423	355L-2	2985	524,82	3726,23	7,1	1007,79	1612,46	1,6	2217,14	2,2	95,2	94,9	94,0	95,0	0,910	0,890	0,870	75	103	3,85000	2300,0



4 Poles

IE2, high efficiency class IE 60034-30

[suitable for variable speed drive duty]

data at 400V 50Hz

KW	HP	Type	rpm	In (A)	Is (A)	Is In	Cn (Nm)	Cs (Nm)	Cs Cn	Cmax (Nm)	Cmax Cn	η %			min IE2	Pwr. Fact. cosφ			ΔT (°C)	LwA (dB)	J Kgm ²	Kg
												100%	75%	50%		100%	75%	50%				
0,09	0,12	56B-4	1346	0,33	0,97	2,9	0,64	1,80	2,8	1,80	2,8	60,7	58,0	43,0	-	0,647	0,540	0,360	36	52	0,00040	3,6
0,13	0,18	63A-4	1355	0,40	1,28	3,2	0,92	2,10	2,3	2,10	2,3	64,7	63,9	62,0	-	0,720	0,620	0,590	30	52	0,00050	4,5
0,18	0,25	63B-4	1393	0,56	2,02	3,6	1,23	2,90	2,4	3,10	2,5	68,2	65,9	58,0	-	0,680	0,550	0,400	38	52	0,00060	4,7
0,25	0,35	63C-4	1380	0,72	2,41	3,3	1,73	4,10	2,4	4,00	2,3	71,0	71,3	67,6	-	0,702	0,601	0,468	51	52	0,00075	5,7
0,25	0,35	71A-4	1400	0,69	2,90	4,2	1,71	4,30	2,5	4,57	2,7	72,7	72,0	68,0	-	0,720	0,615	0,500	41	55	0,00080	6,0
0,37	0,5	71B-4	1366	1,04	3,72	3,6	2,59	6,00	2,3	6,10	2,4	71,5	72,0	61,2	-	0,720	0,630	0,412	65	55	0,00130	6,3
0,55	0,75	71C-4	1400	1,47	5,78	3,9	3,75	6,90	1,8	6,60	1,8	74,9	75,3	72,0	-	0,720	0,645	0,500	80	55	0,00170	7,3
0,55	0,75	80A-4	1391	1,49	6,46	4,3	3,78	9,10	2,4	10,20	2,7	75,0	75,4	73,0	-	0,710	0,610	0,500	50	58	0,00180	10,0
0,75	1	80B-4	1394	1,99	7,57	3,8	5,14	12,50	2,4	12,65	2,5	79,6	79,4	74,0	79,6	0,685	0,606	0,456	77	58	0,00231	11,0
1,1	1,5	80C-4	1390	2,85	11,03	3,9	7,56	18,70	2,5	12,70	1,7	81,5	81,7	77,9	81,4	0,684	0,560	0,440	86	58	0,00248	12,5
1,1	1,5	90S-4	1378	2,50	9,89	4,0	7,62	16,20	2,1	17,53	2,3	81,4	83,2	81,5	81,4	0,779	0,642	0,541	78	61	0,00253	13,0
1,5	2	90L-4	1413	3,54	18,44	5,2	10,14	27,60	2,7	31,05	3,1	82,9	84,0	82,8	82,8	0,738	0,642	0,531	46	61	0,00297	14,0
1,9	2,6	90LB-4	1415	4,47	23,24	5,2	12,82	24,61	1,9	26,50	2,1	84,3	84,6	82,0	84,3	0,728	0,630	0,488	55	61	0,00495	16,0
2,2	3	100LA-4	1435	4,80	25,82	5,4	14,64	33,20	2,3	41,87	2,9	84,4	84,5	82,1	84,3	0,784	0,668	0,546	68	64	0,00594	23,0
3	4	100LB-4	1407	6,39	27,93	4,4	20,36	41,20	2,0	30,12	1,5	85,5	87,9	87,1	85,5	0,793	0,700	0,550	94	64	0,00744	25,0
4	5,5	112M-4	1415	7,75	39,24	5,1	27,00	51,40	1,9	40,79	1,5	86,6	89,0	86,8	86,6	0,860	0,800	0,720	76	65	0,01055	28,0
5	6,8	112MB-4	1445	10,02	63,50	6,3	33,04	82,70	2,5	71,14	2,2	87,7	88,7	87,9	87,7	0,821	0,750	0,640	77	65	0,01667	35,0
5,5	7,5	132S-4	1446	10,74	61,43	5,7	36,32	69,00	1,9	74,88	2,1	87,8	89,5	88,5	87,7	0,842	0,780	0,660	83	71	0,02378	45,0
7,5	10	132M-4	1450	14,38	91,41	6,4	49,40	97,00	2,0	99,00	2,0	88,8	89,7	70,0	88,7	0,848	0,800	0,700	92	71	0,03289	47,0
9,2	12,5	132MB-4	1426	16,71	95,09	5,7	61,61	123,30	2,0	97,88	1,6	89,9	92,2	92,6	89,8	0,884	0,850	0,784	96	72	0,03444	55,0
11	15	132MC-4	1461	21,96	170,43	7,8	71,90	196,40	2,7	186,95	2,6	89,8	89,8	87,8	89,8	0,805	0,770	0,610	80	73	0,04444	57,0
11	15	160M-4	1460	21,67	134,07	6,2	71,95	153,40	2,1	208,66	2,9	89,8	89,4	87,6	89,8	0,816	0,776	0,654	70	75	0,06777	118,0
15	20	160L-4	1456	28,12	178,96	6,4	98,39	197,10	2,0	245,96	2,5	90,8	91,7	90,6	90,6	0,848	0,810	0,717	72	75	0,10199	132,0
18,5	25	180M-4	1476	34,45	215,02	6,2	119,70	220,90	1,8	334,30	2,8	91,2	91,1	89,9	91,2	0,850	0,810	0,723	51	76	0,15443	164,0
22	30	180L-4	1470	39,57	202,00	5,1	142,93	255,00	1,8	357,31	2,5	91,6	91,6	90,8	91,6	0,876	0,847	0,775	75	76	0,17554	182,0
30	40	200L-4	1475	53,84	323,02	6,0	194,24	388,47	2,0	505,02	2,6	93,2	93,0	91,5	92,3	0,863	0,816	0,765	73	79	0,29108	245,0
37	50	225S-4	1480	66,07	345,00	5,2	238,75	501,38	2,1	573,00	2,4	92,8	93,3	92,3	92,7	0,871	0,840	0,777	91	81	0,45107	258,0
45	60	225M-4	1480	79,02	437,00	5,5	290,37	570,00	2,0	710,00	2,4	93,3	93,3	92,1	93,1	0,881	0,863	0,799	70	81	0,52106	290,0
55	75	250M-4	1480	97,61	585,64	6,0	354,90	674,31	1,9	816,27	2,3	93,7	96,1	93,0	93,5	0,868	0,841	0,780	75	83	0,73326	388,0
75	100	280S-4	1484	129,70	648,48	5,0	482,65	854,00	1,8	915,00	1,9	94,1	94,2	92,2	94,0	0,887	0,860	0,840	80	80	1,43000	510,0
90	120	280M-4	1485	152,96	747,77	4,9	578,79	1041,82	1,8	1150,00	2,0	94,7	94,7	94,7	94,2	0,897	0,889	0,854	54	86	1,63900	606,0
110	150	315S-4	1489	189,80	1138,79	6,0	705,51	1481,56	2,1	1834,32	2,6	95,1	94,6	92,6	94,5	0,880	0,860	0,803	71	93	3,44300	910,0
132	180	315M-4	1485	224,09	1174,96	5,2	848,89	1612,89	1,9	2207,11	2,6	95,2	95,3	94,7	94,7	0,893	0,875	0,831	55	93	4,01500	1000,0
160	220	315LA-4	1485	276,24	1906,08	6,9	1028,96	2160,81	2,1	2263,70	2,2	95,0	94,5	94,0	94,9	0,880	0,850	0,800	80	97	4,52320	1055,0
200	270	315LB-4	1481	339,92	2345,45	6,9	1289,67	2708,31	2,1	2837,27	2,2	95,1	94,7	93,8	95,1	0,893	0,885	0,844	75	97	5,29100	1128,0
250	335	355M-4	1483	420,03	2898,23	6,9	1609,91	3380,82	2,1	3541,81	2,2	95,6	95,4	94,7	95,1	0,899	0,897	0,874	80	101	7,18300	1700,0
315	423	355L-4	1490	524,91	3621,87	6,9	2018,96	4239,82	2,1	4441,71	2,2	95,7	95,5	94,7	95,1	0,905	0,883	0,818	70	101	9,06400	1900,0

KW	HP	Type	rpm	In (A)	Is (A)	Is / In	Cn (Nm)	Cs (Nm)	Cs / Cn	Cmax (Nm)	Cmax / Cn	η %			min IE2	Pwr. fact. cosφ			ΔT (°C)	LwA (dB)	J Kg·m ²	Kg
												100%	75%	50%		100%	75%	50%				
0,18	0,25	71A-6	921	0,66	1,93	2,9	1,87	4,20	2,3	4,30	2,3	62,7	61,1	53,7	-	0,631	0,540	0,418	41	51	0,00110	6,0
0,25	0,35	71B-6	910	0,87	2,62	3,0	2,62	6,00	2,3	6,00	2,3	64,0	62,5	57,1	-	0,650	0,550	0,426	54	51	0,00140	6,3
0,37	0,5	80A-6	928	1,20	3,58	3,0	3,81	6,80	1,8	8,10	2,1	67,3	66,0	60,9	-	0,660	0,562	0,451	58	53	0,00160	10,0
0,55	0,75	80B-6	917	1,71	4,72	2,8	5,73	10,40	1,8	10,60	1,9	70,5	71,4	67,7	-	0,658	0,574	0,440	80	53	0,00190	11,0
0,75	1	90S-6	915	2,01	5,98	3,0	7,83	13,00	1,7	9,97	1,3	76,0	77,9	75,2	75,9	0,710	0,610	0,480	69	57	0,00319	13,0
1,1	1,5	90L-6	915	2,74	9,93	3,6	11,48	22,10	1,9	16,57	1,4	78,3	80,2	79,3	78,1	0,740	0,650	0,560	67	57	0,00385	14,0
1,5	2	100L-6	944	3,91	16,15	4,1	15,17	29,39	1,9	35,09	2,3	79,9	80,3	77,6	79,8	0,693	0,609	0,477	71	58	0,00759	23,0
2,2	3	112M-6	951	5,45	25,84	4,7	22,09	45,40	2,1	57,79	2,6	81,9	82,7	80,4	81,8	0,712	0,610	0,475	74	61	0,01540	25,0
3	4	132S-6	969	6,95	38,23	5,5	29,57	62,40	2,1	81,20	2,7	84,5	84,6	82,1	83,3	0,737	0,710	0,536	63	64	0,03146	28,0
4	5,5	132MA-6	969	8,85	56,55	6,4	39,42	89,90	2,3	121,80	3,1	84,7	84,5	82,0	84,6	0,770	0,690	0,566	76	64	0,03927	45,0
5,5	7,5	132MB-6	966	12,38	65,09	5,3	54,37	103,20	1,9	95,28	1,8	87,0	87,5	87,0	86,0	0,737	0,653	0,545	64	64	0,04961	55,0
7,5	10	160M-6	978	16,97	88,24	5,2	73,24	109,85	1,5	146,47	2,0	88,6	89,2	88,5	87,2	0,720	0,670	0,600	50	71	0,08910	118,0
11	15	160L-6	970	23,37	106,35	4,6	108,30	173,28	1,6	184,11	1,7	89,5	90,5	89,9	88,7	0,759	0,700	0,582	70	71	0,12760	125,0
15	20	180L-6	984	29,79	140,65	4,7	145,58	232,93	1,6	334,83	2,3	89,8	89,4	88,0	89,7	0,809	0,750	0,657	75	73	0,22770	160,0
18,5	25	200LA-6	970	35,28	183,46	5,2	182,14	327,85	1,8	454,99	2,5	91,0	90,8	89,7	90,4	0,832	0,781	0,685	60	76	0,34650	217,0
22	30	200LB-6	982	42,61	215,40	5,1	213,95	385,11	1,8	534,88	2,5	91,1	91,0	89,3	90,9	0,818	0,763	0,668	80	76	0,39600	244,0
30	40	225M-6	980	55,62	236,55	4,3	292,35	503,00	1,7	518,00	1,8	91,8	91,6	92,0	91,7	0,848	0,828	0,759	60	76	0,60170	295,0
37	50	250M-6	983	68,00	297,27	4,4	359,46	611,08	1,7	718,92	2,0	92,6	92,3	92,4	92,2	0,848	0,828	0,759	56	78	0,92730	365,0
45	60	280S-6	982	78,93	360,33	4,6	437,63	700,20	1,6	919,02	2,1	93,2	93,6	92,2	92,7	0,883	0,865	0,813	42	80	1,52900	500,0
55	75	280M-6	985	96,24	459,99	4,8	533,25	853,20	1,6	1119,82	2,1	93,1	93,6	93,2	93,1	0,886	0,873	0,822	71	80	1,81500	545,0
75	100	315S-6	986	132,96	534,60	4,0	726,42	1162,27	1,6	1307,56	1,8	94,5	95,1	94,4	93,7	0,862	0,860	0,820	70	85	4,52100	810,0
90	125	315MA-6	985	159,67	1069,81	6,7	872,59	1745,18	2,0	1745,18	2,0	94,6	94,5	93,6	94,0	0,860	0,831	0,766	75	85	5,25800	900,0
110	150	315LA-6	985	195,78	1311,71	6,7	1066,50	2132,99	2,0	2132,99	2,0	94,3	93,9	93,7	94,3	0,860	0,840	0,820	80	85	5,99500	1010,0
132	180	315LB-6	985	233,94	1567,40	6,7	1279,80	2559,59	2,0	2559,59	2,0	94,7	94,2	93,7	94,6	0,860	0,840	0,810	80	85	6,73200	1140,0
160	220	355MA-6	990	279,71	1874,08	6,7	1543,43	2932,53	1,9	3086,87	2,0	94,9	94,2	93,3	94,8	0,870	0,870	0,850	80	92	10,45000	1550,0
200	270	355MB-6	990	341,43	2287,55	6,7	1929,29	3665,66	1,9	3858,59	2,0	95,0	94,5	94,0	95,0	0,890	0,870	0,850	80	92	11,44000	1600,0
250	335	355L-6	990	431,63	2891,93	6,7	2411,62	4582,07	1,9	4823,23	2,0	95,0	95,0	94,0	95,0	0,880	0,860	0,840	80	92	13,64000	1700,0

KW	HP	Type	rpm	In (A)	Is (A)	Is In	Cn (Nm)	Cs (Nm)	Cs Cn	Cmax (Nm)	Cmax Cn	η %			Pwr. fact. cosφ			ΔT (°C)	LwA (dB)	J Kgm ²	Kg
												100%	75%	50%	100%	75%	50%				
0,13	0,18	71B-8	651	0,71	1,48	2,1	1,91	3,80	2,0	3,93	2,1	48,2	44,9	39,0	0,550	0,460	0,390	76	52	0,00080	6,3
0,18	0,25	80A-8	694	0,83	2,01	2,4	2,48	4,70	1,9	5,50	2,2	56,1	51,0	44,7	0,560	0,460	0,392	54	52	0,00180	10,0
0,25	0,35	80B-8	691	1,10	2,62	2,4	3,46	6,90	2,1	7,06	2,2	61,0	58,2	52,2	0,540	0,450	0,373	56	52	0,00190	11,0
0,37	0,5	90S-8	670	1,41	5,65	4,0	5,27	10,55	2,0	10,55	2,0	62,0	61,0	54,0	0,610	0,550	0,350	40	54	0,00210	13,0
0,55	0,75	90L-8	701	2,04	6,25	3,1	7,49	15,50	2,1	18,00	2,4	68,3	66,0	58,1	0,570	0,490	0,366	22	54	0,00240	14,0
0,75	1	100LA-8	712	2,24	8,66	3,9	10,06	21,70	2,2	25,09	2,5	75,9	75,1	70,3	0,636	0,550	0,426	47	57	0,00900	23,0
1,1	1,5	100LB-8	702	3,38	12,14	3,6	14,96	31,30	2,1	35,91	2,4	73,9	73,4	68,5	0,635	0,524	0,397	65	57	0,01000	25,0
1,5	2	112M-8	711	4,21	16,94	4,0	20,15	43,80	2,2	50,70	2,5	79,2	79,8	79,0	0,650	0,550	0,500	48	61	0,02450	28,0
2,2	3	132S-8	710	5,54	33,23	6,0	29,59	53,26	1,8	59,18	2,0	81,9	82,2	80,0	0,700	0,660	0,481	80	64	0,03140	45,0
3	4	132M-8	716	7,25	31,48	4,3	40,01	71,90	1,8	93,01	2,3	83,0	83,9	82,2	0,720	0,650	0,494	63	64	0,03950	55,0
4	5,5	160MA-8	720	9,32	55,94	6,0	53,06	100,81	1,9	106,11	2,0	86,0	85,8	84,0	0,720	0,640	0,600	75	68	0,07530	110,0
5,5	7,5	160MB-8	720	12,22	53,10	4,3	72,95	145,90	2,0	145,90	2,0	86,6	87,3	85,0	0,750	0,710	0,610	75	68	0,09310	120,0
7,5	10	160L-8	720	16,33	70,97	4,3	99,48	198,96	2,0	198,96	2,0	87,2	88,1	85,0	0,760	0,740	0,720	75	68	0,12600	135,0
11	15	180L-8	730	23,48	129,17	5,5	143,90	287,81	2,0	287,81	2,0	87,8	87,9	87,5	0,770	0,700	0,650	80	70	0,20300	160,0
15	20	200L-8	730	31,03	204,78	6,6	196,23	392,47	2,0	392,47	2,0	89,5	89,4	87,8	0,780	0,709	0,580	75	73	0,33900	235,0
18,5	25	225S-8	730	38,48	253,99	6,6	242,02	459,84	1,9	484,04	2,0	91,3	91,5	90,5	0,760	0,720	0,680	80	73	0,49100	242,0
22	30	225M-8	730	44,84	295,97	6,6	287,81	546,84	1,9	575,62	2,0	91,3	91,6	90,6	0,776	0,727	0,608	70	73	0,54700	285,0
30	40	250M-8	730	59,32	391,51	6,6	392,47	745,68	1,9	784,93	2,0	92,4	92,3	91,0	0,790	0,760	0,720	80	75	0,84300	390,0
37	50	280S-8	730	74,02	488,53	6,6	484,04	919,68	1,9	968,08	2,0	92,5	92,4	91,0	0,780	0,730	0,670	80	76	1,93000	500,0
45	60	280M-8	740	89,93	593,51	6,6	580,74	1045,34	1,8	1161,49	2,0	92,6	92,6	89,7	0,780	0,730	0,680	80	76	1,65000	580,0
55	75	315S-8	740	104,10	687,05	6,6	709,80	1277,64	1,8	1419,59	2,0	93,0	93,0	92,0	0,820	0,760	0,650	80	82	4,79000	790,0
75	100	315M-8	740	142,91	943,23	6,6	967,91	1742,23	1,8	1935,81	2,0	93,4	92,8	91,1	0,811	0,744	0,614	70	82	5,58000	970,0
90	125	315LA-8	740	168,57	1112,56	6,6	1161,49	2090,68	1,8	2322,97	2,0	93,8	93,3	91,6	0,822	0,769	0,641	75	82	6,37000	1055,0
110	150	315LB-8	740	205,82	1317,24	6,4	1419,59	2555,27	1,8	2839,19	2,0	94,4	94,1	92,7	0,817	0,754	0,629	80	82	7,23000	1118,0
132	180	355MA-8	740	247,97	1587,01	6,4	1703,51	3066,32	1,8	3407,03	2,0	93,7	93,7	93,1	0,820	0,820	0,760	80	82	7,60000	2000,0
160	220	355MB-8	740	298,97	1913,44	6,4	2064,86	3716,76	1,8	4129,73	2,0	94,2	94,2	93,5	0,820	0,820	0,760	80	82	7,70000	2150,0
200	270	355L-8	740	368,04	2355,48	6,4	2581,08	4645,95	1,8	5162,16	2,0	94,5	94,5	93,0	0,830	0,830	0,790	80	82	8,20000	2250,0
250	335	355LB-8	740	467,15	2989,75	6,4	3226,35	5807,43	1,8	6452,70	2,0	94,2	94,2	93,1	0,820	0,820	0,780	80	82	8,30000	2350,0

To get the data double polarity motors, contact our export office.



KW	HP	Type	rpm	In (A)	Is (A)	Is/In	Cn (Nm)	Cs (Nm)	Cs/Cn	Cmax (Nm)	Cmax/Cn	η %			min IE3	Pwr. fact. cosφ			ΔT (°C)	LwA (dB)	J Kgm²	Kg	
												100%	IE	75%		50%	100%	75%					50%
0,75	1	90S-6	941	1,96	8,60	4,4	7,61	18,20	2,4	19,03	2,5	79,1	IE3	79,2	75,9	78,9	0,699	0,570	0,482	40	55	0,00300	23,0
1,1	1,5	90L-6	936	2,86	12,10	4,2	11,22	27,40	2,4	29,18	2,6	81,1	IE3	81,2	77,7	81,0	0,685	0,570	0,438	53	55	0,00360	26,0
1,5	2	100L-6	949	3,53	17,03	4,8	15,09	32,90	2,2	37,74	2,5	83,0	IE3	83,8	82,4	82,5	0,738	0,650	0,526	52	60	0,00850	35,0
2,2	3	112M-6	955	5,28	25,56	4,8	22,00	47,60	2,2	57,20	2,6	84,8	IE3	85,6	84,3	84,3	0,709	0,630	0,498	59	62	0,01600	44,0
3	4	132S-6	971	6,99	38,51	5,5	29,51	58,10	2,0	76,71	2,6	87,6	IE3	88,0	86,7	85,6	0,707	0,611	0,511	39	68	0,02930	67,0
4	5,5	132MA-6	974	9,34	58,39	6,3	39,22	90,90	2,3	125,50	3,2	88,2	IE3	88,0	86,1	86,8	0,701	0,610	0,484	51	68	0,03720	75,0
5,5	7,5	132MB-6	972	12,46	72,99	5,9	54,04	124,29	2,3	156,71	2,9	90,0	IE3	90,1	89,2	88,0	0,708	0,606	0,492	63	69	0,04780	86,0
7,5	10	160M-6	970	15,56	104,25	6,7	73,84	155,06	2,1	162,45	2,2	89,2	IE3	89,3	88,4	89,1	0,780	0,668	0,542	70	72	0,11583	125,0
11	15	160L-6	970	22,26	153,57	6,9	108,30	227,43	2,1	238,26	2,2	90,3	IE3	90,4	89,5	90,3	0,790	0,676	0,549	70	72	0,14674	150,0
15	20	180L-6	980	29,28	210,79	7,2	146,17	292,35	2,0	306,96	2,1	91,3	IE3	91,4	90,5	91,2	0,810	0,693	0,563	70	72	0,26186	200,0
18,5	25	200LA-6	980	35,95	258,84	7,2	180,28	378,59	2,1	396,62	2,2	91,7	IE3	91,8	90,9	91,7	0,810	0,693	0,563	70	72	0,39848	240,0
22	30	200LB-6	980	41,96	306,27	7,3	214,39	450,21	2,1	471,65	2,2	92,3	IE3	92,4	91,5	92,2	0,820	0,702	0,570	70	72	0,45540	260,0
30	40	225M-6	980	56,78	403,15	7,1	292,35	584,69	2,0	613,93	2,1	93,0	IE3	93,1	92,2	92,9	0,820	0,702	0,570	70	73	0,69196	300,0
37	50	250M-6	980	68,07	483,30	7,1	360,56	757,18	2,1	793,23	2,2	93,4	IE3	93,5	92,6	93,3	0,840	0,719	0,584	70	75	1,06640	420,0
45	60	280S-6	980	80,52	579,73	7,2	438,52	920,89	2,1	964,74	2,2	93,8	IE3	93,9	93,0	93,7	0,860	0,736	0,598	70	75	1,75835	540,0
55	75	280M-6	980	97,99	705,55	7,2	535,97	1125,54	2,1	1179,13	2,2	94,2	IE3	94,3	93,4	94,1	0,860	0,736	0,598	70	77	2,08725	620,0
75	100	315S-6	980	134,48	901,05	6,7	730,87	1461,73	2,0	1534,82	2,1	94,7	IE3	94,8	93,9	94,6	0,850	0,728	0,591	70	82	5,19915	855,0
90	125	315MA-6	980	162,79	1090,67	6,7	877,04	1754,08	2,0	1841,79	2,1	95,0	IE3	95,1	94,2	94,9	0,840	0,719	0,584	70	82	6,04670	920,0
110	150	315LA-6	980	196,21	1314,59	6,7	1071,94	2143,88	2,0	2251,07	2,1	95,2	IE3	95,3	94,4	95,1	0,850	0,728	0,591	70	82	6,59450	1111,0
132	180	315LB-6	980	231,98	1554,27	6,7	1286,33	2572,65	2,0	2701,29	2,1	95,5	IE3	95,6	94,7	95,4	0,860	0,736	0,598	70	82	7,40520	1254,0
160	220	355MA-6	980	277,38	1858,42	6,7	1559,18	3118,37	2,0	3274,29	2,1	95,7	IE3	95,8	94,8	95,6	0,870	0,745	0,605	70	84	11,49500	1705,0
200	270	355MB-6	980	346,00	2318,18	6,7	1948,98	3897,96	2,0	4092,86	2,1	95,9	IE3	96,0	95,0	95,8	0,870	0,745	0,605	70	84	12,58400	1760,0
250	335	355L-6	980	432,50	2897,72	6,7	2436,22	4872,45	2,0	5116,07	2,1	95,9	IE3	96,0	95,0	95,8	0,870	0,745	0,605	70	85	15,00400	1870,0

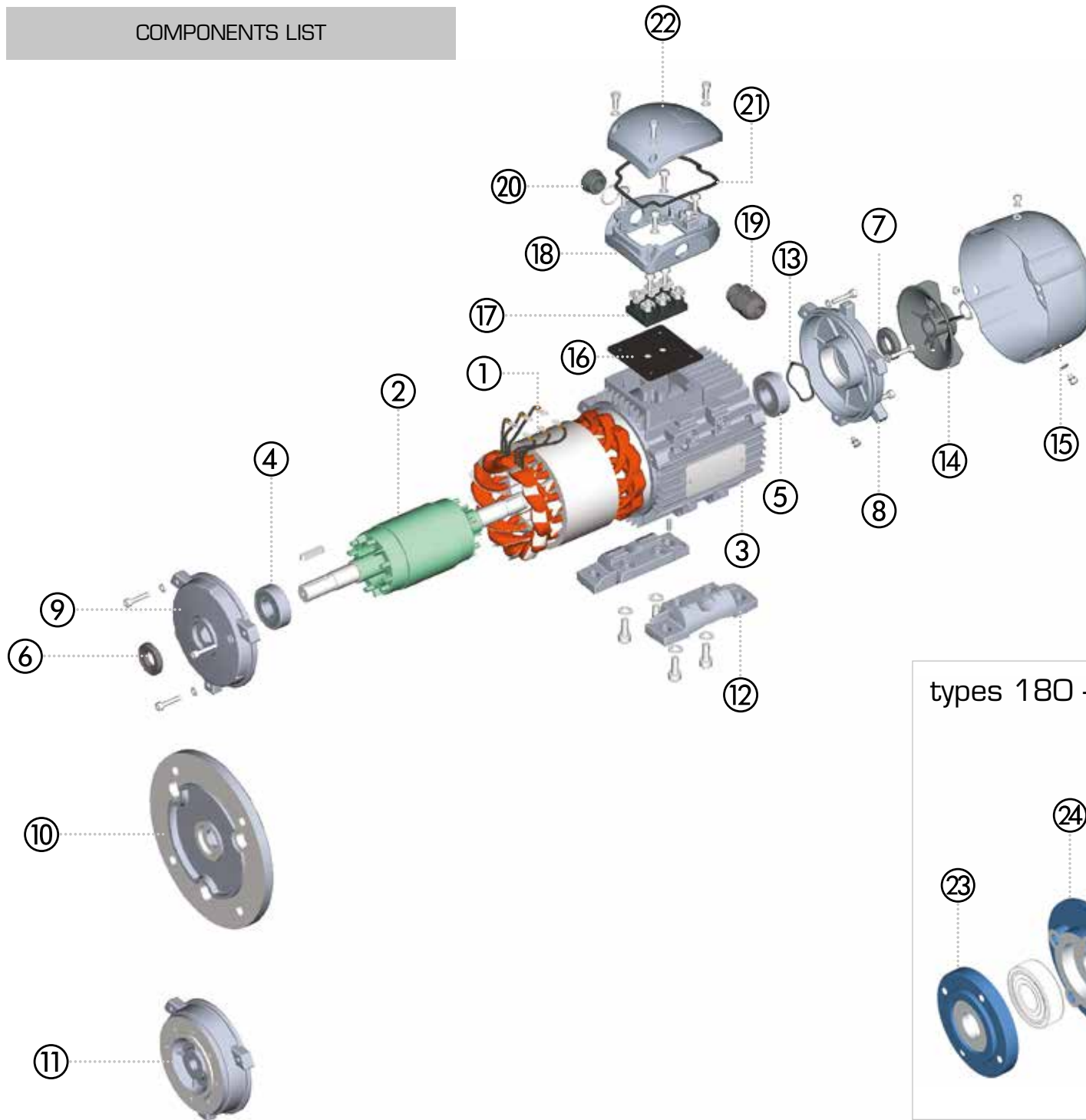


The technical files with all performance data and PDF drawings of each motor, can be downloaded from www.motive.it "datasheet creator" section



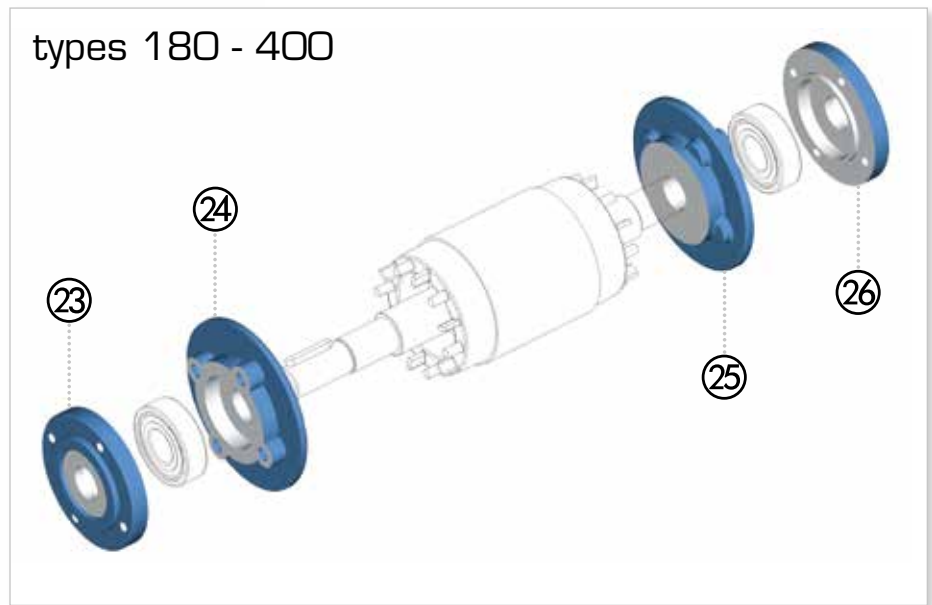
NOTE: motors can be improved in any moment. The data in www.motive.it can be more updated. Each data is even more detailed and proven by the type test reports loaded in www.motive.it

COMPONENTS LIST



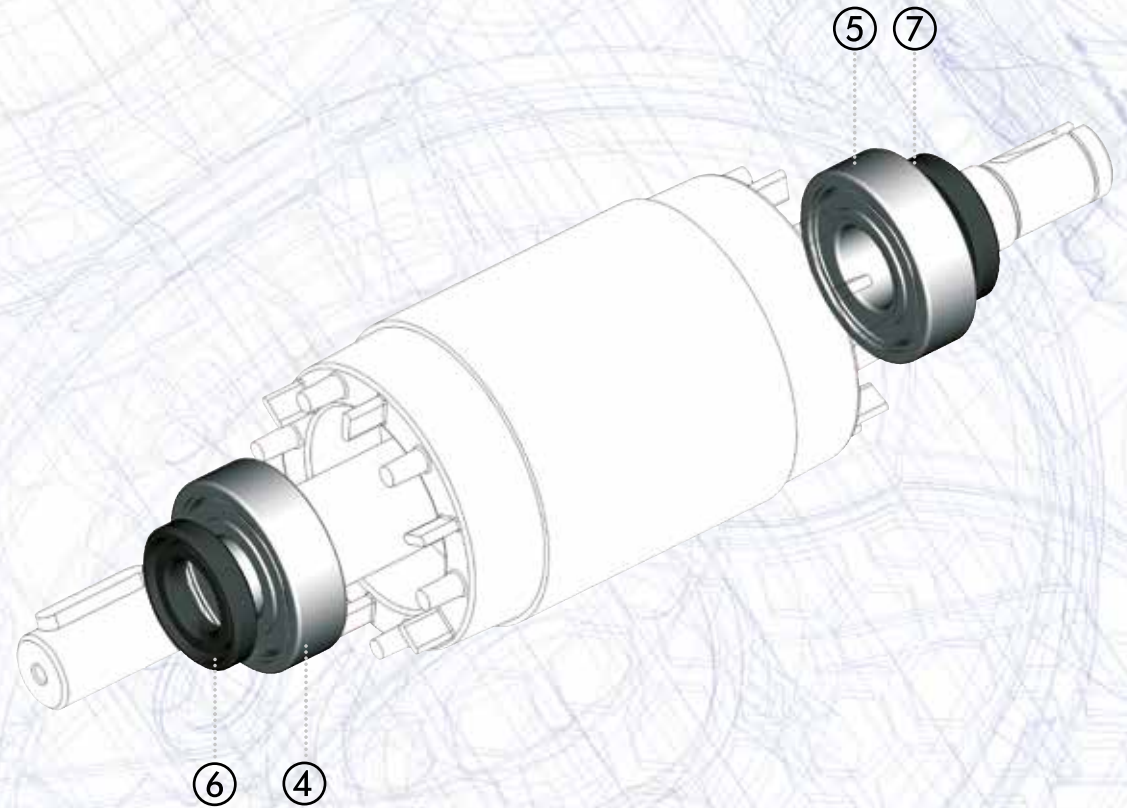
N°	CODE
1	3PNSTA
2	3PNROT
3	3PNFRA
4	3PNFBE
5	3PNBBE
6	3PNFOS
7	3PNBOS
8	3PNBSH
9	3PNBO3
10	3PNBO5
11	3PNB14
12	3PNFEE
13	3PNWAV

N°	CODE
14	3PNFAN
15	3PNFCV
16	3PNUCB
17	3PNTER
18	3PNBCB
19	3PNCMP
20	3PNCAP
21	3PNSCB
22	3PNCCB
23	3PNFOB
24	3PNFIB
25	3PNBIB
26	3PNBOB



RUBBER SEAL RINGS AND BEARINGS

FRAME SIZE	POLES NUMBER	RUBBER SEAL RING		BEARINGS	
		⑥	⑦	④	⑤
56	2 - 8	12x24x7	12x24x7	6201 ZZ-C3	6201 ZZ-C3
63	2 - 8	12x24x7	12x24x7	6201 ZZ-C3	6201 ZZ-C3
71	2 - 8	15x30x7	15x26x7	6202 ZZ-C3	6202 ZZ-C3
80	2 - 8	20x35x7	20x35x7	6204 ZZ-C3	6204 ZZ-C3
90	2 - 8	25x40x7	25x40x7	6205 ZZ-C3	6205 ZZ-C3
100	2 - 8	30x47x7	30x47x7	6206 ZZ-C3	6206 ZZ-C3
112	2 - 8	30x47x7	30x47x7	6206 ZZ-C3	6206 ZZ-C3
132	2 - 8	40x62x8	40x62x8	6208 ZZ-C3	6208 ZZ-C3
160	2 - 8	45x62x8	45x62x8	6309 ZZ-C3	6309 ZZ-C3
180	2 - 8	55x72x8	55x72x8	6311-C3	6311-C3
200	2 - 8	60x80x8	60x80x8	6312-C3	6312-C3
225	2 - 8	65x80x10	65x80x10	6313-C3	6313-C3
250	2 - 8	70x90x10	70x90x10	6314-C3	6314-C3
280	2	70x90x10	70x90x10	6314-C3	6314-C3
280	4 - 8	85x100x12	85x100x12	6317-C3	6317-C3
315	2	85x110x12	85x110x12	6317-C3	6317-C3
315	4 - 8	95x120x12	95x120x12	NU 319-C3	6319-C3
355	2	95x120x12	95x120x12	6319-C3	6319-C3
355	4 - 8	110x130x12	110x130x12	NU 322-C3	6322-C3
400	4 - 8	130x160x12	130x160x12	NU 326-C3	6326-C3



"bearing lubrication devices" are an optional.







TERMS OF SALE AND GUARANTEE

ARTICLE 1 GARANTEE

1.1. Barring written agreements, entered into between the parties hereto each time, Motive hereby guarantees compliance of products supplied and compliance with specific agreements. The guarantee for defects shall be restricted to product defects following design, materials or manufacturing defects leading back to Motive.

The Guarantee shall not include:

-  faults or damages ensuing from transport., faults or damages ensuing from installation defects; incompetent use of the product, or any other unsuitable use.
-  tampering or damages ensuing from use by non - authorised staff and/or use of non - original parts and/or spare parts;
-  Defects and/or damages ensuing from chemical agents and/or atmospheric phenomena (e.g. burnt out material, etc.); routine maintenance and required action or checks;
-  Products lacking a plate or having a tampered plate.

1.2. Returns to credit or replace will be accepted only in exceptional cases; However returns of goods already used to credit or replace won't be accepted in any case. The guarantee shall be effective for all Motive products, with a term of validity of 12 months, starting from the date of shipment. The guarantee shall be subject to specific written request for Motive to take action, according to statements, as described at the paragraphs hereinbelow. By virtue of aforesaid approval, and as regards the claim, Motive shall be bound, at its discretion, and within a reasonable time-limit, to alternatively take the following action:

- a) To supply the Buyer with products of the same type and quality as those having proven defective and not complying with agreements, free ex-works; in aforesaid case, Motive shall have the right to request, at the Buyer's charge, early return of defective goods, which shall become Motive's property;
- b) To repair, at its charge, the defective product or to modify the product which does not comply with agreements, by performing aforesaid action at its facilities; in aforesaid cases, all costs regarding product transport shall be sustained by the Buyer.
- c) To send spare parts free of charge: all costs regarding product transport shall be sustained by the Buyer.

1.3 The guarantee herein shall assimilate and replace legal guarantees for defects and discrepancies, and shall exclude any other eventual Motive liability, however caused by supplied products; in particular, the Buyer shall have no right to submit any further claims. Motive shall not be liable for the enforcement of any further claims, as of the date the guarantee's term of validity expires.

ARTICLE 2 CLAIMS

2.1. Without prejudice to the application of provisions in Law, dated June 21, 1971, and as per Article 1:
Claims, regarding quantity, weight, gross weight and colour, or claims regarding faults and defects in quality or compliance, and which the Buyer may discover on goods delivery, shall be submitted by a max. 7 days of aforesaid discovery, under penalty of nullity.

ARTICLE 3 DELIVERY

3.1. Any liability for damages ensuing from total or partial delayed or failed delivery, shall be excluded.

3.2. Unless differently communicated by written to the Client, the transport terms have to be intended ex-works

ARTICLE 4 PAYMENT

4.1. Any delayed or irregular payments shall entitle Motive to cancel ongoing agreements, including agreements which do not regard the payments at issue, as well as entitling Motive to claim damages, if any. Motive shall, however, have the right, as of the payment's due date and without placing in arrears, to claim interest for arrears, to the extent of the discount rate in force in Italy, increased by 5 points. Motive shall also have the right to withhold material under repair for replacement. In the case of failed payment, Motive shall have the right to cancel all guarantees on materials, as regards the insolvent Client.

4.2. The Buyer shall be bound to complete payment, including cases whereby claims or disputes are underway.

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ASK OUR FURTHER CATALOGUES:



Motive s.r.l.

Via Le Ghiselle, 20

25014 Castenedolo (BS) - Italy

Tel.: +39.030.2677087 - Fax: +39.030.2677125

web site: www.motive.it

e-mail: motive@motive.it



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